

BREGMAN PROXIMAL ALGORITHMS FOR COMPOSITE AND FINITE-SUM NONCONVEX MINIMIZATION PROBLEMS

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BREGMAN PROXIMAL ALGORITHMS

FOR COMPOSITE AND FINITE-SUM NONCONVEX MINIMIZATION PROBLEMS



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First-Order Methods with Convergence Analysis @ SIAM OP21

July 22, 2021

Outline

Proximal algorithm(s)

Proximal point algorithm

Simplest analysis

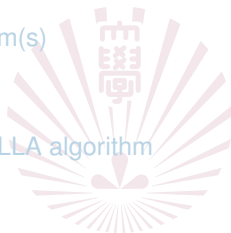
Bregman proximal algorithm(s)

Why Bregman

Linesearch B-FBS: the BELLA algorithm

Newton-type?

Linesearch?



Block-coordinate B-FBS: Bregman Finito/MISO

Conclusions

Proximal algorithm(s)

Proximal point algorithm

Problem

$$\underset{x \in \mathbb{R}^n}{\text{minimize}} \varphi(x)$$

(P)

A1. $\varphi : \mathbb{R}^n \rightarrow \overline{\mathbb{R}}$ proper, lsc

A2. $\inf \varphi > -\infty$

Proximal mapping

$$\text{prox}_{\gamma\varphi}(x) = \arg \min_{w \in \mathbb{R}^n} \left\{ \varphi(w) + \frac{1}{2\gamma} \|w - x\|^2 \right\} : \mathbb{R}^n \rightrightarrows \mathbb{R}^n \quad (\gamma > 0)$$

Method

Proximal point algorithm (PPA)

$$x^{k+1} \in \text{prox}_{\gamma\varphi}(x^k)$$

Proximal algorithm(s)

Proximal point algorithm: simplest convergence analysis

Tool

Moreau envelope

$$\varphi^\gamma(x) = \min_{w \in \mathbb{R}^n} \left\{ \varphi(w) + \frac{1}{2\gamma} \|w - x\|^2 \right\} : \mathbb{R}^n \rightarrow \mathbb{R}$$

P1. $\varphi^\gamma \leq \varphi$

P3. φ^γ **continuous**

P2. $\varphi^\gamma(x) = \varphi(\bar{x}) + \frac{1}{2\gamma} \|\bar{x} - x\|^2$

P4. $\frac{x - \bar{x}}{\gamma} \in \hat{\partial}\varphi(\bar{x})$ ($\bar{x} \in \text{prox}_{\gamma\varphi}(x)$)

Convergence of PPA

$$x^{k+1} \in \text{prox}_{\gamma\varphi}(x^k)$$

$$\varphi(x^{k+1})$$

$$\hat{\partial}\varphi(z) = \left\{ v \mid \liminf_{z \neq w \rightarrow z} \frac{\varphi(w) - \varphi(z) - \langle v, w - z \rangle}{\|w - z\|} \geq 0 \right\}$$
 is the (Fréchet) subdifferential of φ at z

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$$\varphi^\gamma(x^{k+1}) \stackrel{\text{P1}}{\leq} \varphi(x^{k+1})$$

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Proximal algorithm(s)

Proximal point algorithm: simplest convergence analysis

PPA

φ proper, lsc, lower bounded

$$x^{k+1} \in \text{prox}_{\gamma\varphi}(x^k)$$

ω set of limit points of $(x^k)_{k \in \mathbb{N}}$:

1. $\varphi(x^k), \varphi^\gamma(x^k) \searrow \varphi_\star$
2. $\varphi \equiv \varphi^\gamma \equiv \varphi_\star$ on ω
3. $0 \in \partial\varphi(x^\star)$ for any $x^\star \in \omega$
4. φ **coercive** $\Rightarrow (x^k)_{k \in \mathbb{N}}$ bounded, and $\omega \neq \emptyset$ compact & connected

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PPA _{λ} (λ -relaxed PPA)

$$\begin{cases} \bar{x}^k \in \text{prox}_{\gamma\varphi}(x^k) \\ x^{k+1} = (1 - \lambda)x^k + \lambda\bar{x}^k \end{cases} \xRightarrow{\text{same arguments}^\star} \varphi^\gamma(x^{k+1}) \leq \varphi^\gamma(x^k) - \frac{\lambda(2-\lambda)}{2\gamma} \|\bar{x}^k - x^k\|^2$$

All the claims of **PPA** hold for **PPA _{λ}** for any $\lambda \in (0, 2)$

$^\star \varphi^\gamma(x^+) \leq \varphi(\bar{x}) + \frac{1}{2\gamma} \|\bar{x} - x^+\|^2 = \varphi^\gamma(x) - \frac{1}{2\gamma} \|\bar{x} - x\|^2 + \frac{1}{2\gamma} \|\bar{x} - x^+\|^2 = \varphi^\gamma(x) - \frac{\lambda(2-\lambda)}{2\gamma} \|\bar{x} - x\|^2$

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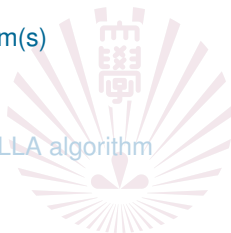
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Bregman proximal algorithm(s)

Why? ~ Structured problems

Proximal Point

- 😊 extremely simple analysis
- 😞 not “practical”: $\text{prox}_{\gamma\varphi}$ usually hard to compute

Proximal gradient method (AKA Forward-backward splitting)

In many applications, $\varphi = \text{“smooth } f\text{”} + \text{“easy-to-prox } g\text{”}$

$$\begin{aligned}x^{k+1} &\in \text{prox}_{\gamma g} \left(x^k - \gamma \nabla f(x^k) \right) \\&= \arg \min_{w \in \mathbb{R}^n} \left\{ f(x^k) + \langle \nabla f(x^k), w - x^k \rangle + g(w) + \frac{1}{2\gamma} \|w - x^k\|^2 \right\}\end{aligned}$$

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$\hat{h} := \frac{1}{2\gamma} \|\cdot\|^2 - f$ strongly convex when $\gamma < 1/L_f$

$$\mathbf{D}_h(z, x) := h(z) - h(x) - \langle \nabla h(x), z - x \rangle$$

for a convex $h \in C^1(\mathbb{R}^n)$ is the Bregman distance induced by h

Bregman proximal algorithm(s)

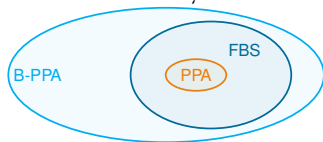
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FBS = Bregman PPA

with **d**fg $\hat{h} = \frac{1}{2\gamma} \|\cdot\|^2 - f$



Bregman proximal algorithm(s)

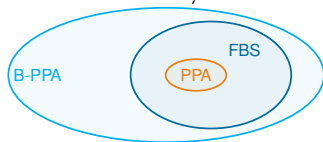
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with dfg $\hat{h} = \frac{1}{2\gamma} \|\cdot\|^2 - f$



- ✓ Same results of **PPA** $\gamma < 1/L_f$
 $\left\{ \begin{array}{ll} \frac{1}{2\gamma} \|\cdot\|^2 \rightarrow D_{\hat{h}} \\ \varphi^\gamma \rightarrow \varphi^{\hat{h}} := \min_w \left\{ \varphi(w) + D_{\hat{h}}(w, \cdot) \right\} \end{array} \right.$
- ✓ For **FBS** $_\lambda$: take $0 < \lambda < \frac{2}{1+\gamma L_f}$

$$\varphi^{\hat{h}}(x^+) \leq \varphi^{\hat{h}}(x) - \frac{2-\lambda(1+\gamma L_f)}{\lambda(1-\gamma L_f)} D_{\hat{h}}(x^+, x)$$

- ✓ ($\varphi^{\hat{h}}$ is the **forward-backward envelope**)

P. Patrinos and A. Bemporad, *Proximal Newton methods for convex composite optimization*, In: 52th IEEE CDC, 2013

AT, L. Stella and P. Patrinos, *Forward-Backward Envelope for the Sum of Two Nonconvex Functions: Further Properties and Nonmonotone Linesearch Algorithms*, SIAM J Opt 28(3):2274-2303, 2018

Bregman proximal algorithm(s)

Why? ~ ...

With a suitable h

✓ **Uni-simplify** analysis

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► Can enforce $x^k \in \text{dom } h$: blend proximal and barrier methods

$$\underset{x \in \mathbb{R}^n}{\text{minimize}} \varphi(x) \quad \text{s.t.} \quad x \in C$$

where C is the closure of $\text{dom } h$

^{a lot!}
~~some~~ caution if φ nonconvex

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✓ **Uni-simplify** analysis

≈ M. Teboulle, *A simplified view of first order methods for optimization*, MathProg **170**(1):67–96, Springer, **2018**

► Can enforce $x^k \in \text{dom } h$: blend proximal and barrier methods

$$\underset{x \in \mathbb{R}^n}{\text{minimize}} \varphi(x) \quad \text{s.t.} \quad x \in C$$

where C is the closure of $\text{dom } h$

(~~some~~ ^{a lot!} caution if φ nonconvex)

✓ Extend applicability

✓ make prox tractable

✓ relax assumptions

f is L_f -**relative smooth** wrt h if $L_f h \pm f$ are convex

Bregman proximal algorithm(s)

Why? ~ ...

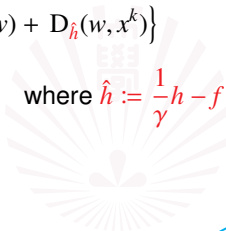
Bregman FBS

f L_f -smooth relative to a dgf h

$$x^{k+1} \in \arg \min_{w \in \mathbb{R}^n} \left\{ f(x^k) + \langle \nabla f(x^k), w - x^k \rangle + g(w) + \frac{1}{\gamma} D_h(w, x^k) \right\}$$

$$= \arg \min_{w \in \mathbb{R}^n} \left\{ \varphi(w) + D_{\hat{h}}(w, x^k) \right\}$$

$$= \text{prox}_{\varphi}^{\hat{h}}(x^k) \quad \text{where } \hat{h} := \frac{1}{\gamma} h - f$$



Bregman proximal algorithm(s)

Why? ~ ...

Bregman FBS

f L_f -smooth relative to a dgf h

$$\begin{aligned}x^{k+1} &\in \arg \min_{w \in \mathbb{R}^n} \left\{ f(x^k) + \langle \nabla f(x^k), w - x^k \rangle + g(w) + \frac{1}{\gamma} D_h(w, x^k) \right\} \\&= \arg \min_{w \in \mathbb{R}^n} \left\{ \varphi(w) + D_{\hat{h}}(w, x^k) \right\} \\&= \text{prox}_{\varphi}^{\hat{h}}(x^k) \quad \text{where } \hat{h} := \frac{1}{\gamma} h - f\end{aligned}$$

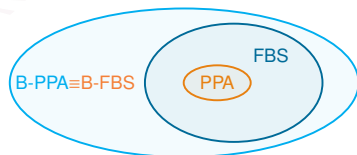
B-BFS $\equiv$ B-PPA

f L_f -smooth relative to dgf h

$$\Rightarrow \hat{h} := \frac{1}{\gamma} h - f \text{ is a dgf}$$

(with same properties)

- ▶ $\text{dom } \hat{h} = \text{dom } h$
- ▶ h (loc.) str.cvx/smooth $\Rightarrow \hat{h}$ (loc.) str.cvx/smooth
- ▶ $D_h(x^k, y^k) \rightarrow 0 \Rightarrow D_{\hat{h}}(x^k, y^k) \rightarrow 0$
- ▶ ...



Outline

Proximal algorithm(s)

Proximal point algorithm

Simplest analysis

Bregman proximal algorithm(s)

Why Bregman

Linesearch B-FBS: the BELLA algorithm

Newton-type?

Linesearch?



Block-coordinate B-FBS: Bregman Finito/MISO

Conclusions

Line search B-FBS: the BELLA algorithm

Problem & objective

Problem

$$\underset{x \in \mathbb{R}^n}{\text{minimize}} \varphi(x)$$

(P)

A1. $\varphi : \mathbb{R}^n \rightarrow \overline{\mathbb{R}}$ proper, lsc

A2. $\inf \varphi > -\infty$

Toolbox

Bregman proximal mapping

$$\text{prox}_{\varphi}^h(x) = \arg \min_{w \in \mathbb{R}^n} \{\varphi(w) + D_h(w, x)\} : \mathbb{R}^n \rightrightarrows \mathbb{R}^n$$

A3. h dgf with $\text{dom } h = \mathbb{R}^n$

Goal

- ▶ Globalize **Newton-type methods** $x^+ = x + \tau d$
- ▶ by using **only** the **B-PPA** oracle

Line search B-FBS: the BELLA algorithm

Newton type?

$$x^+ = x + \tau d$$

But...

- ☹ φ^h usually **nonsmooth**
- ☹ or, anyway, $\nabla \varphi^h = \nabla^2 h [\text{id} - \text{prox}_{\varphi}^h]$
 - ▶ even if applicable, Armijo-type line search would require $\nabla^2 h$
 - ▶ (this was the original approach of **minFBE**)

Directions

Necessary optimality condition: $0 \in R_{\varphi}^h(x^*) := [\text{id} - \text{prox}_{\varphi}^h](x^*)$

$\Rightarrow$ Get d via **quasi-Newton** on R_{φ}^h

Requires (only)

- ✓ prox_{φ}^h
- ✓ direct linear algebra (scalar products)

Line search B-FBS: the BELLA algorithm

Line search?

$$x^+ = x + \tau d$$

Still...

- ☹ φ^h usually **nonsmooth**
- ☹ or, anyway, $\nabla \varphi^h = \nabla^2 h [\text{id} - \text{prox}_\varphi^h]$
- ☹ is d of “descent”?

And yet...

- 😊 φ^h is **continuous**
- 😊 $\varphi^h(\bar{x}) \leq \varphi(\bar{x}) = \varphi^h(x) - D_h(\bar{x}, x)$ $(\bar{x} \in \text{prox}_\varphi^h(x))$

Line search B-FBS: the BELLA algorithm

Line search?

$$\cancel{x^+ = x + \tau d}$$

Still...

- ☹ φ^h usually **nonsmooth**
- ☹ or, anyway, $\nabla \varphi^h = \nabla^2 h [\text{id} - \text{prox}_\varphi^h]$
- ☹ is d of “descent”?

And yet...

- 😊 φ^h is **continuous**
- 😊 $\varphi^h(\bar{x}) \leq \varphi(\bar{x}) = \varphi^h(x) - D_h(\bar{x}, x)$

$$(\bar{x} \in \text{prox}_\varphi^h(x))$$

Solution (works for **any** d !)

$$x^+ = (1 - \tau)\bar{x} + \tau(x + d)$$

reducing τ until

$$\varphi^h(x^+) \leq \varphi^h(x) - \sigma D_h(\bar{x}, x) \quad (\sigma \in (0, 1) \text{ fixed})$$

LineSearch B-FBS: the BELLA algorithm

The BELLA algorithm

Bregman Envelope LineSearch Algorithm

1. $\bar{x} \in \text{prox}_{\varphi}^h(x)$
2. Choose $d \in \mathbb{R}^n$ and set $\tau = 1$
3. **While** $\varphi^h((1 - \tau)\bar{x} + \tau(x + d)) \geq \varphi^h(x) - \sigma D_h(\bar{x}, x)$ **do**
 $\tau \leftarrow \tau/2$
4. $x^+ = (1 - \tau)\bar{x} + \tau(x + d)$

Convergence

$$\varphi^h(x^{k+1}) \leq \varphi^h(x^k) - \sigma D_h(\bar{x}^k, x^k) \quad (\text{SD})$$

Same convergence properties of **(B)-PPA**!

Extras...

(under assumptions)

- ▶ global/ R -linear with **KL**
- ▶ If directions d are “good”, $\tau = 1$ eventually always accepted

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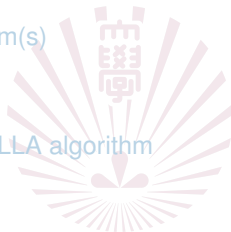
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Block coordinate B-FBS

Regularized finite-sum

Problem
$$\underset{x \in \mathbb{R}^n}{\text{minimize}} \varphi(x) \equiv \frac{1}{N} \sum_{i=1}^N f_i(x) + g(x) \quad (\text{P})$$

A1. $g : \mathbb{R}^n \rightarrow \overline{\mathbb{R}}$ proper, lsc

A2. f_i L_{f_i} -smooth relative to a dgf h_i

A3. $\inf \varphi > -\infty$

Consensus formulation

$$\underset{x \in \mathbb{R}^{nN}}{\text{minimize}} \Phi(x) \equiv \overbrace{\frac{1}{N} \sum_{i=1}^N f_i(x_i)}^{F(x)} + \overbrace{\frac{1}{N} \sum_{i=1}^N g(x_i)}^{G(x)} + \delta_{\Delta}(x) \quad (\text{P}_{\Delta})$$

$\Delta := \{x \in \mathbb{R}^{nN} \mid x_1 = x_2 = \dots = x_N\}$ is the **consensus set**

Block coordinate B-FBS

Bregman Finito/MISO

Block-coordinate B-PPA (or B-FBS)

with dgf $\hat{H} := \hat{h}_1 \times \dots \times \hat{h}_N$ $\hat{h}_i := \frac{1}{\gamma_i} h_i - f_i$, $\gamma_i \in (0, N/L_{f_i})$

1. $\mathbf{u} \in \text{prox}_{\hat{\Phi}}^{\hat{H}}(\mathbf{x})$ % B-PPA = B-FBS
2. select/sample $i \in \{1, \dots, N\}$
3. $x_j^+ = \begin{cases} u_i & \text{if } j = i, \\ x_j & \text{otherwise} \end{cases}$

Block coordinate B-FBS

Bregman Finito/MISO

Block-coordinate B-PPA (or B-FBS)

with $\text{dof } \hat{H} := \hat{h}_1 \times \dots \times \hat{h}_N \quad \hat{h}_i := \frac{1}{\gamma_i} h_i - f_i, \quad \gamma_i \in (0, N/L_{f_i})$

1. $\mathbf{u} \in \text{prox}_{\hat{\Phi}}^{\hat{H}}(\mathbf{x})$ % B-PPA = B-FBS
2. select/sample $i \in \{1, \dots, N\}$
3. $x_j^+ = \begin{cases} u_i & \text{if } j = i, \\ x_j & \text{otherwise} \end{cases}$

Not wasteful! it is Bregman MISO/Finito⁺

1. $\mathbf{z} \in \arg \min_w \left\{ g(w) + \sum_i \frac{1}{\gamma_i} h_i(w) - \langle \tilde{\mathbf{s}}, w \rangle \right\}$

2. select/sample $i \in \{1, \dots, N\}$

3. update gradients table

$$s_j^+ = \begin{cases} \frac{1}{\gamma_i} \nabla h_i(\mathbf{z}) - \frac{1}{N} \nabla f_i(\mathbf{z}) & \text{if } j = i, \\ s_j & \text{otherwise} \end{cases}$$

4. update aggregated B-FBS step $\tilde{\mathbf{s}}^+ = \tilde{\mathbf{s}} + (s_i^+ - s_i)$

- ✓ nonsmooth/nonconvex g
- ✓ independent stepsizes γ_i
- ✓ relative-smooth f_i

Block coordinate B-FBS

Convergence results

For ANY sampling

- ✓ Decrease on $\Phi^{\hat{H}}$
- ✓ φ coercive $\Rightarrow$ bounded sequence

Randomized/Shuffled/Cyclic

- ✓ Sufficient decrease on $\Phi^{\hat{H}}$
 - ✓ Convergence results of **(B)-PPA** apply!
 - ✓ (including global/ R -linear with **KL**)

Extras...

- ✓ Q -linear rates with φ strongly convex (g or f_i can even be **nonconvex!**)

Analysis agnostic to “our” decomposition of φ !

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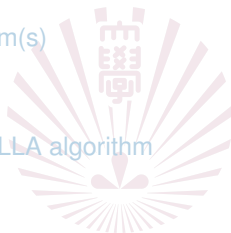
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Conclusions

In this talk...

What we knew

- ▶ Proximal point: elegant, simple, and powerful
- ▶ Bregman divergence: the key enhancement

What we knew but maybe didn't care

- ▶ **B-PPA = B-FBS**
- ▶ Separating tasks: $\overbrace{\text{minimize } \varphi}^{\text{analysis}}$ VS $\overbrace{\text{minimize } f + g \dots \text{ s.t. } \dots}^{\text{algorithm}}$

What maybe we didn't know

- ▶ Continuity + sufficient decrease $\rightarrow$ globalize fast local methods
 - 😊 the **BELLA** algorithm
- ▶ Block-coordinate proximal point $\rightarrow$ incremental proximal algorithms
 - 😊 **Bregman MISO/Finito**⁺

M. Ahookhosh, AT and P. Patrinos, *A Bregman Forward-Backward Linesearch Algorithm for Nonconvex Composite Optimization: Superlinear Convergence to Nonisolated Local Minima*, SIAM J Opt **31**(1):653-685, **2021**

P. Latafat, AT, M. Ahookhosh and P. Patrinos, *Bregman Finito/MISO for nonconvex regularized finite sum minimization without Lipschitz gradient continuity*, arXiv:2102.10312, **2021**