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Abstract

Varying-coefficient models are useful tools for analyzing longitudinal data. They can effectively describe a relationship between predictors and responses repeatedly measured. We consider the problem of selecting variables in the varying-coefficient models via the adaptive elastic net regularization. Coefficients given as functions are expressed by basis expansions, and then parameters involved in the model are estimated by the penalized likelihood method using the coordinate descent algorithm derived for solving the problem of sparse regularization. We examine the effectiveness of our modeling procedure through Monte Carlo simulations and real data analysis.

Key Words and Phrases: Basis expansion, Elastic net, Group lasso, Varying-coefficient model.

1 Introduction

Longitudinal data analysis has been used in various fields such as bioscience, ergonomics and meteorology. In longitudinal studies the data are measured repeatedly over time for individual and they have possibly different time points, which makes it difficult to directly apply the traditional multivariate analysis. Enormous works have contributed to the development of longitudinal data analysis during the past few decades (see, e.g. Diggle, 2002). In this article we focus on the problem of selecting variables which seem to have a relation with a response which is repeatedly measured.

Several methods have been proposed for the analysis of longitudinal data. Laird and Ware (1982) introduced random effects models and their estimation procedures and Zeger and Diggle (1994) applied semiparametric models as the regression models for longitudinal data. Ramsay and Silverman (2005) considered treating longitudinal data as smooth functions, and then established the Functional Data Analysis (FDA). On the other hand, Hoover et al. (1998) generalized the semiparametric model and applied the time varying-coefficient model. It is a special case of the varying-coefficient models (Hastie and Tibshirani, 1993) and obtained for analyzing longitudinal data. They approached

the modeling by use of kernel smoothing or smoothing splines with an L_2 -type penalty. Huang et al. (2002) also used smoothing splines for time varying-coefficient models and suggested a non-iterative solution for coefficient estimates. The effectiveness of varying coefficient models are reported in several works (Fan and Zhang, 1999; Cai et al., 2000; Eubank et al., 2004).

More recently, a class of sparse regularization has come to be used for the varyingcoefficient modeling. Sparse regularization including the lasso (Tibshirani, 1996), SCAD (Fan and Li, 2001) and the elastic net (Zou and Hastie, 2005) simultaneously shrinks parameters and selects variables which seem to be relevant to a response by estimating coefficients of rest of the variables to be exactly zeros, and therefore it is one of the most attractive methods in recent years. More details of sparse regularization can be seen in Hastie et al. (2009). We can apply the sparse regularization to the varying-coefficient models by expressing coefficient functions by basis expansions and then imposing L_1 type penalties to coefficient vectors. Since each variable has multiple parameters in this case, Wang et al. (2007b) treated this problem as the grouped variable selection and then applied the idea of the group lasso by Yuan and Lin (2006). They also selected the transcriptional factors involved in gene regulation during a biological process. Wei et al. (2011) applied the adaptive lasso penalty (Zou, 2006) and then estimated the model by the coordinate descent algorithm (Friedman et al., 2007) which is derived for the sparse regularization problem. Many other works concerning the varying-coefficient modeling with the sparse regularization have been reported (Wang et al., 2008; Noh and Park, 2010; Xue and Qu, 2012; Wang et al., 2013).

In this paper we propose a method for estimating and selecting models simultaneously by the varying-coefficient modeling along with the elastic net regularization by extending the method by Wei et al. (2011). Especially we use an adaptive elastic net penalty proposed by Zou and Zhang (2009). They combined the idea of the elastic net and the adaptive lasso in the framework of the general linear model. The adaptive elastic net regularization can select variables even if the number of variables is much larger than the sample size and can take into account highly correlated predictors. Furthermore its estimates has an preferable property called the "oracle property." By applying the elastic net regularization to the varying-coefficient model we can prevent its estimation from giving unstable or degenerate results owing to both L_1 and L_2 terms of the penalty. Coefficient functions of varying-coefficient models are expressed by basis expansions, and then parameters are estimated by the penalized maximum likelihood method with the help of the coordinate descent algorithm. In order to select tuning parameters involved in the adaptive elastic net penalty we use a Bayesian model selection criterion derived for evaluating the varying-coefficient model. The proposed modeling strategy is applied to Monte Carlo simulations and clinical investigation data to investigate the effectiveness of our method.

This paper is organized as follows. In Section 2 we introduce a varying-coefficient model which describe the relationship between multiple predictors and a response repeatedly measured. Section 3 provides a method for estimating the varying-coefficient model with the adaptive elastic net regularization and selecting tuning parameters. Monte Carlo simulations are conducted in Section 4 in order to evaluate the effectiveness of the proposed modeling strategy and real data analysis are described in Section 5. Finally concluding remarks are given in Section 6.

2 Varying-coefficient models

Suppose we have p sets of predictors X_k (k = 1, ..., p) and a response Y, each of them are repeatedly observed at possibly different time points. Denote i-th of n individuals at j-th of n_i time points of X_k and Y as x_{ijk} and y_{ij} respectively. The varying-coefficient model (Hoover et al., 1998) that represents the relationship between X_k s and Y is given by

$$y_{ij} = \beta_0(t_{ij}) + x_{ij1}\beta_1(t_{ij}) + \dots + x_{ijp}\beta_p(t_{ij}) + \varepsilon_{ij}, \tag{1}$$

where $\beta_0(\cdot)$ is an intercept and $\beta_1(\cdot), \ldots, \beta_p(\cdot)$ are coefficients, both of which are given as functions to be estimated. Moreover, ε_{ij} are random noises whose vector $\boldsymbol{\varepsilon}_i = (\varepsilon_{i1}, \ldots, \varepsilon_{in_i})'$ are normally distributed with mean vector $\boldsymbol{0}$ and variance covariance matrix $\sigma^2 S_i$ with unknown scalar σ^2 and known $n_i \times n_i$ symmetric matrix S_i .

We assume that coefficient functions $\beta_k(\cdot)$ (k = 0, ..., p) are expressed by basis expansions as follows;

$$\beta_k(t_{ij}) = \sum_{m=1}^{M_k} \gamma_{km} \phi_m^{(k)}(t_{ij}) = \gamma_k' \phi^{(k)}(t_{ij}),$$

where $\boldsymbol{\gamma}_k = (\gamma_{k1}, \dots, \gamma_{kM_k})'$ are coefficient vectors and $\boldsymbol{\phi}^{(k)}(t_{ij}) = (\phi_1^{(k)}(t_{ij}), \dots, \phi_{M_k}^{(k)}(t_{ij}))'$ are basis functions. There are several basis functions available for $\boldsymbol{\phi}^{(k)}(t)$ such as wavelets or radial basis functions. Here we apply cubic *B*-spline bases, whose details are referred to de Boor (2001); Imoto and Konishi (2003). Using this assumption and denoting $\boldsymbol{y}_i = (y_{i1}, \dots, y_{in_i})'$, $D_{ik} = \operatorname{diag}(x_{i1k}, \dots, x_{in_ik})$ $(k = 1, \dots, p)$, $D_{i0} = I_{n_i}$ and $\Phi_{ik} = (\boldsymbol{\phi}^{(k)}(t_{i1}), \dots, \boldsymbol{\phi}^{(k)}(t_{in_i}))'$, the varying-coefficient model (1) can be rewritten as

$$\boldsymbol{y}_i = \sum_{k=0}^p D_{ik} \Phi_{ik} \boldsymbol{\gamma}_k + \boldsymbol{\varepsilon}_i, \qquad \boldsymbol{\varepsilon}_i \sim N_{n_i}(\boldsymbol{0}, \sigma^2 S_i).$$

Then we have a probability density function

$$f(\boldsymbol{y}_{i}|\boldsymbol{\theta}) = \frac{1}{(2\pi\sigma^{2})^{n_{i}/2}|S_{i}|^{1/2}} \exp\left\{-\frac{1}{2\sigma^{2}} \left(\boldsymbol{y}_{i} - \sum_{k=0}^{p} D_{ik} \Phi_{ik} \boldsymbol{\gamma}_{k}\right)' S_{i}^{-1} \left(\boldsymbol{y}_{i} - \sum_{k=0}^{p} D_{ik} \Phi_{ik} \boldsymbol{\gamma}_{k}\right)\right\},$$
(2)

where we denote a vector of unknown parameters by $\boldsymbol{\theta} = \{\boldsymbol{\gamma}_0, \dots, \boldsymbol{\gamma}_p, \sigma^2\}$. After obtaining an estimator of $\boldsymbol{\theta}$, denoted by $\hat{\boldsymbol{\theta}}$, by the method described in the next section, we have a statistical model $f(\boldsymbol{y}_i|\hat{\boldsymbol{\theta}})$.

3 Estimation and evaluation via the sparse regularization

Unknown parameters; coefficient vectors γ_k and variance parameter σ^2 , involved in the varying coefficient model are estimated by the maximum penalized likelihood method which maximizes a penalized log-likelihood function. The penalized log-likelihood function is given in the form of

$$l_{\lambda}(\boldsymbol{\theta}) = \sum_{i=1}^{n} \log f(\boldsymbol{y}_{i}|\boldsymbol{\theta}) - n\lambda \sum_{k=1}^{p} P_{\alpha}(\|\boldsymbol{\gamma}_{k}\|),$$

where $P_{\alpha}(\cdot)$ is a penalty function, $\|\cdot\|$ is a standard L_2 norm and $\lambda > 0$ is a regularization parameter which controls the degree of the penalty. We impose the penalty composed by a sum of penalty functions of L_2 norms of the coefficient vectors $\boldsymbol{\gamma}_k$ instead of its components separately. Then we can shrink all elements of the vector $\boldsymbol{\gamma}_k$ towards exactly zeros when the corresponding predictor seems to be less relevant to the response. It is exactly the idea of the group lasso by Yuan and Lin (2006). For the penalty function P_{α} we use an adaptive elastic net penalty (Zou and Zhang, 2009) given by

$$P_{\alpha}(\theta) = \frac{1}{2}(1 - \alpha)\theta^2 + \alpha \hat{w}_k |\theta|$$
(3)

for all $\theta \in \mathbb{R}$, where $\alpha \in [0,1]$ tunes the type of the penalty between the ridge $(\alpha = 0)$ and the lasso $(\alpha = 1)$. Furthermore, $\hat{w}_k > 0$ is an adaptive weight which is given in the form of $\hat{w}_k = (\sqrt{M_k} \| \boldsymbol{\gamma}_k \|)^{-\beta} (\| \boldsymbol{\gamma}_k \| \neq 0), = \infty (\| \boldsymbol{\gamma}_k \| = 0)$ with a positive constant β , where we use $\beta = 1$ in this paper.

We have difficulty in analytical expressions for the estimates of coefficients of regression models via the L_1 -type regularization. Wang et al. (2007b) used a local quadratic approximation (Fan and Li, 2001) for the varying-coefficient modeling via the group SCAD regularization, and Wei et al. (2011) applied a coordinate descent procedure (Friedman et al., 2007) to the group adaptive lasso regularization. The coordinate descent method has similar algorithm to the backfitting algorithm, used in the varying coefficient modeling (Hastie and Tibshirani, 1993), in that it updates coefficients of each variable in turn. Using this method, we obtain updated values of k-th coefficients (k = 1, ..., p) as

$$\hat{\boldsymbol{\gamma}}_{k} = \left(\sum_{i=1}^{n} \Phi'_{ik} D_{ik} S_{i}^{-1} D_{ik} \Phi_{ik} + n(1-\alpha) \lambda \hat{\sigma}^{2} I\right)^{-1} \left(\|\boldsymbol{\zeta}_{k}\| - n\alpha \lambda \hat{w}_{k} \hat{\sigma}^{2}\right)_{+} \frac{\boldsymbol{\zeta}_{k}}{\|\boldsymbol{\zeta}_{k}\|}, \tag{4}$$

where

$$oldsymbol{\zeta}_k = \sum_{i=1}^n \Phi_{ik}' D_{ik} S_i^{-1} \left(oldsymbol{y}_i - \sum_{l
eq k}^p D_{il} \Phi_{il} \hat{oldsymbol{\gamma}}_l
ight)$$

and $z_{+} = \max\{z, 0\}$ for $z \in \mathbb{R}$. Both of two terms of the adaptive elastic net penalty (3) directly have effects to the estimates (4) of the varying-coefficient model. The L_1 term of the penalty shrinks some of coefficients γ_k towards zero vectors, while the L_2 term prevents the degeneracy of the inverse, especially when there are few time points for individual and a large number of basis functions. Although the first term in the inverse matrix of (4) does not always degenerate even if n < p unlike the ordinal linear model, the L_2 term of the elastic net penalty provides stable estimates. Note that when k = 0 there is no regularization and therefore $\hat{\gamma}_0$ has the form of (4) with a generalized inverse and $\lambda = 0$. The variance parameter is then estimated in the following form:

$$\hat{\sigma}^2 = \frac{1}{\sum_i n_i} \sum_{i=1}^n \left(\boldsymbol{y}_i - \sum_{k=0}^p D_{ik} \Phi_{ik} \hat{\boldsymbol{\gamma}}_k \right)' S_i^{-1} \left(\boldsymbol{y}_i - \sum_{k=0}^p D_{ik} \Phi_{ik} \hat{\boldsymbol{\gamma}}_k \right). \tag{5}$$

Since $\hat{\gamma}_k$ and $\hat{\sigma}^2$ depend on each other, they are updated until a convergence condition is achieved. Consequently, the algorithm is given as follows:

- 1. Initialize parameters $\gamma_0, \gamma_1, \ldots, \gamma_p$ and σ^2 by 1 for all elements.
- 2. For $k = 0, 1, \dots, p$, update γ_k by (4) in turn.
- 3. Update σ^2 by (5).
- 4. Iterate 2 and 3 until convergence.

Thus the statistical model is obtained by substituting the estimators $\hat{\boldsymbol{\theta}} = \{\hat{\boldsymbol{\gamma}}_0, \dots, \hat{\boldsymbol{\gamma}}_p, \hat{\sigma}^2\}$ given above into the probability density function (2), that is,

$$f(\boldsymbol{y}_i|\hat{\boldsymbol{\theta}}) = \frac{1}{(2\pi\hat{\sigma}^2)^{n_i/2}|S_i|^{1/2}} \exp\left\{-\frac{1}{2\hat{\sigma}^2} \left(\boldsymbol{y}_i - \sum_{k=0}^p D_{ik} \Phi_{ik} \hat{\boldsymbol{\gamma}}_k\right)' S_i^{-1} \left(\boldsymbol{y}_i - \sum_{k=0}^p D_{ik} \Phi_{ik} \hat{\boldsymbol{\gamma}}_k\right)\right\}.$$

The statistical model estimated by the adaptive elastic net regularization depends on the regularization parameter, the tuning parameter and the number of basis functions, therefore we need to decide these values objectively. The decision problem is regarded as a model selection or evaluation problem. Although a cross validation is widely used for the model selection problem, it often selects unstable estimates and has high computational burden. Wang et al. (2007a) showed that GCV does not select the true model consistently and that BIC consistently select the true model for the SCAD regularization. We apply

the BIC for selecting the regularization parameter λ , tuning parameter α and the number of basis functions M_k . Model selection criterion BIC has the form of

BIC =
$$-2\sum_{i=1}^{n} \log f(Y|\hat{\theta}) + edf \log n$$

= $-\log(2\pi\hat{\sigma}^2)\sum_{i=1}^{n} n_i - \sum_{i=1}^{n} \log|S_i| - \sum_{i=1}^{n} n_i + edf \log n,$ (6)

where edf is an effective degrees of freedom for the varying-coefficient model. Matsui et al. (2013) derived an effective degrees of freedom for the varying coefficient models estimated by the regularization method with the L_2 penalty. Applying this result, the effective degrees of freedom for the varying coefficient models estimated by the adaptive elastic net regularization is given by

$$edf = \sum_{i=1}^{n} \sum_{k=1}^{p} \operatorname{tr} \left\{ D_{ik} \Phi_{ik} \left(\sum_{i=1}^{n} \Phi'_{ik} D_{ik} S_{i}^{-1} D_{ik} \Phi_{ik} + n(1-\alpha) \lambda \hat{\sigma}^{2} I_{M_{k}} \right)^{-1} \right.$$
$$\left(\| \boldsymbol{\zeta}_{k} \| - n\alpha \lambda \hat{w}_{k} \hat{\sigma}^{2} \right)_{+} \frac{1}{\| \boldsymbol{\zeta}_{k} \|} \Phi'_{ik} D_{ik} S_{i}^{-1} \right\}.$$

4 Simulation study

Monte Carlo simulations are conducted in order to examine the effectiveness of our modeling procedure. We generated a repeated measurement data set $\{(\boldsymbol{x}_{ij}, y_{ij}); i = 1, \ldots, n, j = 1, \ldots, n_i\}$, where $\boldsymbol{x}_{ij} = (x_{ij0}, x_{ij1}, \ldots, x_{ijp})'$ with $x_{ij0} = 1$, from a true model

$$y_{ij} = f(\boldsymbol{x}_{ij}) + \varepsilon_{ij}, \quad f(\boldsymbol{x}_{ij}) = \sum_{k=0}^{p} x_{ijk} \beta_k(t_{ij}),$$
$$\varepsilon_{ij} \sim N(0, \sigma^2), \quad \sigma = s \left\{ \max_{i,j} f(\boldsymbol{x}_{ij}) - \min_{i,j} f(\boldsymbol{x}_{ij}) \right\},$$

where we set the number of predictors to be p=50, which only first 30 predictors are relevant to the response. We investigated whether the proposed model appropriately select predictors which is relevant to the response for various values of sample sizes n and variance parameters s.

First, time points t_{ij} were generated from an uniform distribution U(-0.5, 0.5) and their numbers n_i were uniformly generated as integer values between 4 and 15 for each subject i. Then predictors $X_k = X_k(t)$ were generated by following random numbers:

$$X_1(t) \sim U(t/10, 2+t/10),$$
 $X_7(t) \sim N(3\exp(t/30), 1),$ $X_{13}(t) \sim N(t, 1),$ $X_{19}(t) \sim N(\sin(2\pi t) + 2, 1),$ $X_{25}(t) \sim N(\cos(2\pi t) + 2, 1)$

for k = 1, 7, 13, 19, 25 respectively. They are independent of any other variables. Other variables for $k \leq 30$, which are dependent on above variables, are generated from $N((1 + x_{ik'}(t))/(2 + x_{ik'}(t)), 1)$ where $k' = 6\lfloor (k-1)/6 \rfloor + 1$ with a floor function $\lfloor \cdot \rfloor$ for each i. Remaining variables $X_k(t)$ for $k = 31, \ldots, 50$, independent of each other, are generated from a multivariate normal distribution with mean vector $\mathbf{0}$ and variance covariance matrix $\operatorname{cov}(X_k(t), X_k(s)) = 4 \exp(-|t-s|/5)$. Next, coefficient functions are set to be

$$\beta_0(t) = \exp(t^3), \qquad \beta_1(t) = 2 + 3\sin(\pi t/60),$$

$$\beta_6(t) = 2 + 3\cos(\pi t/60), \qquad \beta_{11}(t) = 2 - 3\sin(\pi (t - 25)/15),$$

$$\beta_{16}(t) = 2 - 3\cos(\pi (t - 25)/15), \qquad \beta_{21}(t) = 6 - 0.2t^2,$$

$$\beta_{26}(t) = -4 + (20 - t)^3/2000.$$

Other coefficients for $k \leq 30$ are obtained from

$$\beta_k(t) = \beta_{k''}(t) + \boldsymbol{\eta}' \boldsymbol{\psi}(t),$$

where $k'' = 5\lfloor (k-1)/5 \rfloor + 1$ and $\boldsymbol{\psi}(t) = (\psi_1(t), \dots, \psi_5(t))'$ is a vector of cubic *B*-spline basis functions and $\boldsymbol{\eta} = (\eta_1, \dots, \eta_5)'$ is a random variable which follows multivariate normal distribution with mean vector $\mathbf{0}$ and variance covariance matrix $\operatorname{cov}(\eta_i, \eta_j) = 4\exp(-|i-j|/5)$. The remaining coefficients are set to be $\beta_k(t) = 0$ for $k = 31, \dots, 50$, which suggest that the variables X_k for $k = 31, \dots, 50$ are irrelevant to the response. We considered three patterns of sample size n = 15, 25, 50 and two patterns of variance parameter s = 0.05, 0.1.

For the data set, we applied our varying-coefficient modeling procedure with cubic B-spline basis, here we assumed that the number of basis functions $M_k = 6$ for all k. Regularization parameters in the penalized log-likelihood function were selected by BIC given in (6). In order to investigate the effectiveness of the proposed method, we compared results of our modeling procedure with those of the adaptive group lasso. We repeated this procedure for 100 times, and then obtained 100 mean squared errors $\text{MSE} = \sum_i \sum_j \{f(\boldsymbol{x}_{ij}) - \hat{y}_{ij}\}^2 / \sum_i n_i$, where \hat{y}_{ij} is a predictive value of y_{ij} . Furthermore we examined numbers of selected variables and proportions of variables correctly estimated by zero and incorrectly estimated by zero so as to investigate the variable selection performance.

Table 1 shows results of simulation studies. It contains averages and standard deviations of 100 MSEs and selected regularization parameters and averages of tuning parameters. This table also provides numbers of selected variables and proportions that were correctly and incorrectly estimated to be zeros. These results show that our method gives fewer and stable (or competitive) MSEs than the adaptive lasso. The number of selected variables of the adaptive elastic net are larger than that of the adaptive lasso. The proportions of variables correctly estimated to be zeros are fewer than the adaptive lasso,

Table 1: Result of simulation studies. Notations "ave" and "sd" represent average and standard deviation respectively.

	Adaptive elastic net			Adaptive lasso			
\overline{n}	15	25	50	15	25	50	
s = 0.05							
$ave(MSE) \times 10^{-2}$	0.91	2.43	2.60	1.66	3.49	3.37	
$sd(MSE) \times 10^{-2}$	0.76	1.27	1.01	1.60	1.55	1.26	
$ave(\lambda) \times 10^2$	4.21	4.17	2.20	5.96	6.17	2.85	
$sd(\lambda) \times 10^2$	1.48	1.17	0.35	3.45	2.47	1.47	
$ave(\alpha)$	0.85	0.80	0.80				
select	32.42	24.18	25.55	23.10	9.19	12.49	
$\operatorname{correct}$	35.85	67.15	67.95	50.55	92.70	89.90	
incorrect	38.03	44.63	39.53	59.30	77.57	68.43	
s = 0.1							
$ave(MSE) \times 10^{-2}$	1.59	2.61	3.04	2.37	3.37	3.98	
$sd(MSE) \times 10^{-2}$	1.38	1.39	1.33	1.78	1.56	1.38	
$ave(\lambda) \times 10^2$	3.97	4.04	2.25	5.70	5.26	3.50	
$sd(\lambda) \times 10^2$	1.11	1.07	0.49	3.33	1.89	0.20	
$ave(\alpha)$	0.85	0.80	0.80				
select	31.68	23.90	24.59	22.00	10.24	10.57	
$\operatorname{correct}$	38.95	66.60	71.55	55.90	89.10	94.05	
incorrect	38.43	45.93	40.33	59.40	76.47	72.07	

while those incorrectly estimated to be zeros are larger. It suggests that the adaptive elastic net tends to select necessary variables than the adaptive lasso.

5 Real data example

We applied the proposed modeling strategy to the analysis of the multicenter AIDS cohort study data, available on the R package timereg. The aim of the analysis is to investigate the relationship between properties of the human who are infected with the Human Immunodeficiency Virus (HIV) and the percentages of the CD4 cells in their blood. The data set contains cigarette smoking status, age at HIV infection, pre-HIV infection CD4 cell percent and the CD4 cell percentage of each subject, observed at distinct time points after HIV infection. Several researchers have applied the varying-coefficient modeling to the analysis of this data (Fan and Zhang, 2000; Huang et al., 2004; Wang et al., 2008). We applied the varying coefficient model and the group adaptive elastic net regularization in order to investigate which combination of variables is important.

We represent the relationship of variables described above by the time varying-coefficient

Table 2: Selected numbers of each variable for 100 bootstrap samples. "k" denotes the number of the variable. The upper side of the table indicates the result of original variables, while the lower is of artificially appended variables.

\overline{k}	1	2	3	4						
select	0	0	6	100						
\overline{k}	5	6	7	8	9	10	11	12	13	14
select	0	0	0	22	22	4	0	0	6	4

model written by

$$y_i(t) = \sum_{k=0}^{p} x_{ik} \beta_k(t) + \varepsilon_i(t),$$

where predictors x_{ik} represent an overall intercept or baseline (BASE, k=0), observed time (TIME, k=1), age at HIV infection (AGE, k=2), cigarette smoking status represented by 0 or 1 (SMOKE, k=3), and pre-infection CD4 percent (PreCD4, k=4) of the i-th subject, respectively, response $y_i(t)$ is the CD4 percent of the i-th subject observed at differing time points, $\beta_k(t)$ are time varying coefficients and $\varepsilon_i(t)$ are the error functions. We assumed that the variance covariance matrix of the vector $(\varepsilon_i(t_{i1}), \ldots, \varepsilon_i(t_{in_i}))'$ were $\sigma^2 I$. In addition to these original predictors, we appended 10 artificial variables to the predictor by the following method. First, we randomly selected a variable from $X_k, k=2,3,4$ and then assigned a random sample of the selected variable without replacement to a new variable. We repeated this process for 10 times and then treated them as X_k ($k=5,\ldots,14$).

Coefficient functions are supposed to be expressed by cubic B-spline basis expansions. Then the model was fitted by the maximum penalized likelihood method with group adaptive elastic net penalty, and it was evaluated by BIC. In order to avoid time consuming process, we assumed that the number of basis functions was the same among variables and the number of basis functions was set to be 6. We generated 100 sets of bootstrap samples from the data, and then obtained 100 estimates of coefficient functions and numbers of selected variables.

Table 2 shows sums of numbers of selected variables except for BASE (intercept) for 100 repetition. We can find that PreCD4 was most selected and other original predictors were hardly selected. In addition, artificially appended variables were less selected. These results show that PreCD4 strongly has an influence on CD4 cell percentage, while other variables such as SMOKE and AGE have little relevance. Furthermore the proposed method can also appropriately exclude variables which are truly unnecessary.

Estimated coefficients are shown in Figure 1. Solid lines are mean coefficient functions for 100 bootstrap samples and dashed lines are pointwise 90 % confidence intervals. Figure

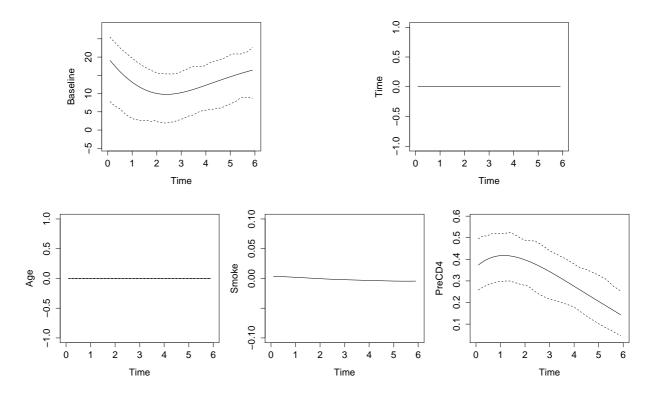


Figure 1: Estimated coefficient functions for original variables. Top left: BASE, top right: TIME, bottom left: AGE, bottom middle: SMOKE, bottom right: PreCD4.

1 suggests that the CD4 data have a trend that decreases with time in early time and then increases gradually, and that PreCD4 has a positive influence on CD4 cell percentage, but it gradually becomes weak with time. On the other hand, TIME, AGE and SMOKE seem to have almost no effect on the CD4 percentage all the time since most coefficients of them are estimated to be exactly zeros. It reveals that these three variables are irrelevant to the CD4 cell percentage. These results are quite similar to those of Wang et al. (2008).

6 Concluding Remarks

In this article, we have applied the sparse regularization to varying-coefficient models in order to select variables repeatedly measured at possibly different time points. We used an adaptive elastic net penalty in the penalized likelihood method, and then parameters involved in the model are estimated by the framework of the coordinate descent algorithm. In order to select regularization parameters involved in the penalized likelihood method, we derived an effective degrees of freedom for the varying coefficient model and then apply a BIC-type criterion. Simulation studies suggest that our modeling strategy worked well in the viewpoint of variable selection and prediction accuracy rather than the existing method. Furthermore we applied it to the analysis of real data and showed that some of information of the HIV patient seems to irrelevant to the CD4 cell percentage.

More recently, Şentürk and Müller (2010) proposed a new type of varying-coefficient models which considers the relationship between a response and predictors with recent time points. Future work will focus on applying the sparse regularization to such models to investigate the time range that the predictors affect the response.

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