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## Shear thickening oscillation in a dilatant fluid

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By introducing a state variable, we construct a phenomenological fluid dynamical model for a dilatant fluid, i.e. a dense mixture of fluid and granules that shows severe shear thickening. We demonstrate that the fluid shows the shear thickening oscillation, namely, the fluid flow oscillates due to the coupling between the fluid dynamics and the internal dynamics of state. We also demonstrate that the jamming leads to a peculiar response to an external impact on the fluid.

**KEYWORDS:** dilatant fluid, fluid dynamics, shear thickening, jamming, oscillatory instability

Dense mixture of starch and water is an ideal material to demonstrate the shear thickening property of the non-Newtonian fluid. It may behave as liquid but is immediately solidified upon sudden application of stress, thus one can even run over the pool filled with the fluid. It is amazing to see that it develops protrusions sticking out of the surface when it is subject to strong vertical vibration,<sup>1,2</sup> and also intriguing that the fluid vibrates spontaneously when one simply pours it out of a container. A source of these unusual behaviors is the severe shear thickening; the viscosity increases almost discontinuously by orders of magnitude at a certain critical shear rate,<sup>3</sup> which makes the fluid behave like a solid upon abrupt deformation. Such severe shear thickening is often found in dense colloid suspensions and granule-fluid mixtures,<sup>4-7</sup> and they have been sometimes called “dilatant fluid” due to the apparent analogy to Reynolds dilatancy of granular media.<sup>8</sup>

Despite its suggestive name, physicists have not reached the microscopic understanding **for** the shear thickening property **of the dilatant fluid**. It was originally proposed that the shear thickening is due to the order-disorder transition of dispersed particles;<sup>4,5,9,10</sup> the viscosity increases when the fluid flow in high shear regime destroys the layered structure that has appeared in lower shear regime. Although there seem to be some situations where this mechanism is responsible to the shear thickening, there are other cases where the layered structure is not observed prior to the shear thickening<sup>11</sup> or no significant changes in the particle ordering are found upon the discontinuous thickening.<sup>12,13</sup> The cluster formation due to hydrodynamic interaction<sup>14-17</sup> and the jamming<sup>3,6,18-22</sup> have been proposed as plausible mechanisms.

There are several peculiar features in the shear thickening shown by a dilatant fluid: (i) the thickening is so severe and instantaneous that it might be used even to make a body armor to stop a bullet,<sup>23</sup> (ii) the relaxation after removal of the external stress occurs within a few seconds, that is not slow but not as instantaneous as in the thickening process, (iii) the thickened state is **almost rigid** and does not allow much elastic deformation unlike a visco-elastic material, (iv) the viscosity shows hysteresis upon changing the shear rate,<sup>7</sup> (v) noisy fluctuations have been observed in response to an external shear stress in the thickening regime.<sup>7,22</sup>

In this report, we construct a phenomenological model in the macroscopic level and examine the fluid dynamical be-

havior of the dilatant fluid. We introduce a state variable that describes an internal state of the fluid phenomenologically, and couple its dynamics with the fluid dynamics. We find that the following two aspects of the model are important: (1) the fluid state changes in response to the shear stress, (2) the state variable changes with the rate proportional to the shear rate. We examine the model behavior in simple configurations, and demonstrate that the model is capable of describing the characteristic features of hydrodynamic behavior and that the fluid shows *the shear thickening oscillation*.

**Model:** Our model is based upon the incompressible Navier-Stokes equation with the viscosity  $\eta(\phi)$  that depends upon the state variable  $\phi$ . The scalar field  $\phi$ , which takes a value in  $[0, 1]$ , represents the local state of the medium. We assume two limiting states: the low viscosity state ( $\phi \sim 0$ ) and the high viscosity state ( $\phi \sim 1$ ). At  $\phi = 1$ , the system is supposed to be jammed and the viscosity diverges.

The state variable  $\phi$  relaxes to a steady value  $\phi_*$  determined by the local shear stress  $S$ ;  $\phi_*$  is supposed to be a continuous and monotonically increasing from 0 to  $\phi_M$  as a function of  $S$  with a characteristic stress  $S_0$ . The limiting value  $\phi_M$  represents the state of the medium in the high stress limit and should depend upon the medium properties such as the packing fraction of the dispersed granules. In the following, we employ the forms

$$\eta(\phi) = \eta_0 \exp \left[ \frac{A\phi}{1-\phi} \right], \quad \phi_*(S) = \phi_M \frac{(S/S_0)^2}{1 + (S/S_0)^2} \quad (1)$$

with a dimensionless constant  $A$ . The Vogel-Fulcher type divergence is assumed in  $\eta(\phi)$  in order to represent the severe thickening, but a detailed functional form is rather arbitrary.

For the simple shear flow configuration as in Fig.1(a) with

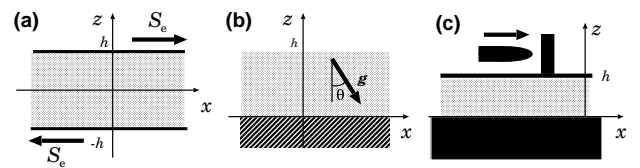


Fig. 1. Flow configurations with the coordinate system. (a) simple shear flow, (b) gravitational slope flow and (c) impact driven flow, where the upper wall is mobilized by a bullet impact.

the flow field given by

$$\mathbf{v} = (u(z, t), 0, 0), \quad (2)$$

the dynamics is described by the set of equations,

$$\rho \frac{\partial u(z, t)}{\partial t} = \frac{\partial}{\partial z} S(z, t), \quad (3)$$

$$\frac{\partial \phi(z, t)}{\partial t} = -\frac{1}{\tau} (\phi(z, t) - \phi_*(S(z, t))), \quad (4)$$

with  $\rho$  and  $\tau$  being the medium density and the relaxation time. The shear stress  $S(z, t)$  is given by

$$S(z, t) = \eta(\phi) \dot{\gamma}, \quad \dot{\gamma} \equiv \frac{\partial u}{\partial z}, \quad (5)$$

where the shear rate is denoted by  $\dot{\gamma}$ .

Now, we suppose the relaxation of  $\phi$  toward  $\phi_*$  is driven by the shear deformation, thus the relaxation rate  $1/\tau$  is not constant but proportional to the absolute value of the shear rate, i.e.

$$1/\tau = |\dot{\gamma}|/r \quad (6)$$

with a dimensionless parameter  $r$ . Note that, with this form of relaxation, the state variable  $\phi$  does not exceed 1 even when  $\phi_M > 1$  because  $\dot{\gamma} \rightarrow 0$  as  $\phi \nearrow 1$  due to the diverging viscosity.

This form of relaxation is natural for the athermal relaxation driven by local deformation. The system responds in accordance with the deformation rate, and does not change the state unless it deforms. This should be valid if the state change is caused by local configurational changes of the dispersed granules due to medium deformation unless Brownian motion plays an important role.

In the following, numerical results are given in the dimensionless unit system where  $\eta_0 = S_0 = \rho = 1$ , i.e. the time, the length, and the mass units are

$$\tau_0 = \eta_0/S_0, \quad \ell_0 = \sqrt{\eta_0 \tau_0 / \rho}, \quad m_0 = \rho \ell_0^3. \quad (7)$$

For the cornstarch suspension of 41 wt%,<sup>3</sup> these may be estimated as  $S_0 \approx 50$  Pa,  $\eta_0 \approx 10$  Pa·s,  $\rho \approx 10^3$  kg/m<sup>3</sup>, which give  $\tau_0 \approx 0.2$  s and  $\ell_0 \approx 5$  cm.

*Steady shear flow:* First, we examine the model behavior in the steady shear flow configuration with a fixed external stress  $S_e$  (Fig.1(a)). The boundary condition is then given by

$$S_e = S(z, t) \Big|_{z=\pm h}. \quad (8)$$

The steady state solution for eqs.(3) and (4) with this boundary condition is obtained easily as

$$\phi = \phi_*(S_e), \quad \dot{\gamma} = \frac{S_e}{\eta(\phi_*)} \equiv \dot{\gamma}_*(S_e). \quad (9)$$

The stress-shear rate curves are plotted in Fig.2 for  $\phi_*$  and  $\eta(\phi)$  of eq.(1) with  $A = 1$  for various values of  $\phi_M$ . In the logarithmic scale, the straight line with the slope 1 corresponds to the linear relation with a constant viscosity. In the curve for  $\phi_M = 0.8$ , one can see the two regimes: the low viscosity regime and the high viscosity regime. Between the two regimes, there is an unstable region. From this stress-shear rate curve, we expect there should be hysteresis upon changing the shear rate  $\dot{\gamma}$  with discontinuous jumps between

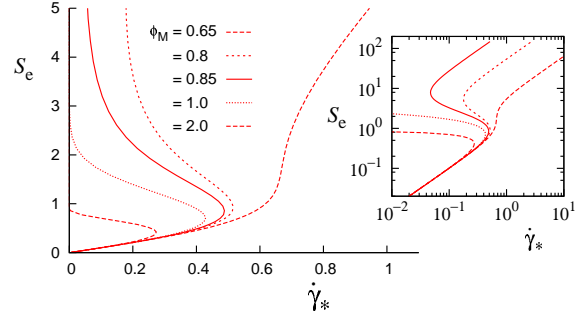


Fig. 2. The stress-shear rate relation for the viscosity given by eq.(1) with  $A = 1$ . The inset shows the same plots in the logarithmic scale.

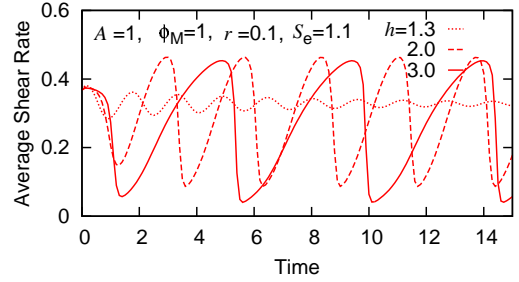


Fig. 3. Oscillation of the average shear rate  $u(h)/h$  in shear flow for  $h=1.3$ , 2, and 3 with  $A = \phi_M = 1$ ,  $r = 0.1$ , and  $S_e = 1.1$ . The initial state is chosen as the steady solution (9) with  $S_e = 1.0$  at  $t = 0$ .

the two branches. The jumps correspond to the discontinuous change of viscosity, i.e. the abrupt shear thickening. For the case  $\phi_M \geq 1$ , the curves do not have an upper linear branch because the viscosity diverges and the fluid is solidified.

*Shear thickening oscillation:* If the external stress  $S_e$  is kept at a value in the unstable branch, where

$$\frac{\partial \dot{\gamma}_*}{\partial S_e} < 0, \quad (10)$$

i.e. the shear rate decreases as the stress increases, the steady flow may become unstable. The linear stability analysis with the perturbation  $\delta \mathbf{v} = (\delta u, 0, 0) e^{i(kz - \omega t)}$  shows that the mode whose wave number  $k$  in the  $z$ -axis satisfies

$$0 < k^2 < \rho \frac{\dot{\gamma}_*}{r} \left[ -\frac{\partial \dot{\gamma}_*}{\partial S_e} \right] \equiv k_c^2 \quad (11)$$

grows and the threshold mode  $k_c$  oscillates at the finite frequency

$$\omega_c = \sqrt{\frac{S_e}{\rho r}} k_c. \quad (12)$$

Since the smallest possible wave number  $k_{\min}$  is given by  $k_{\min} = \pi/(2h)$ , we expect the oscillatory flow appears for  $k_{\min} < k_c$  as the system width increases if the external stress is in the unstable branch.

The oscillatory behavior of the shear flow in the unstable regime can be seen by numerically integrating eqs.(3) and (4) with (8). In Fig.3, the average shear rate  $u(h)/h$  is plotted as a function of time for some values of the system width  $2h$  for  $\phi_M = A = 1$  and  $r = 0.1$  with the external shear stress

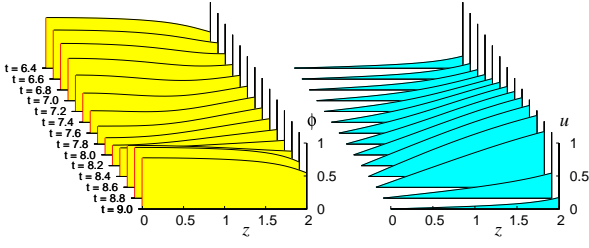


Fig. 4. Spatial variation of shear flow oscillation for  $A = \phi_M = 1$ ,  $r = 0.1$ ,  $S_e = 1.1$ , and  $h = 2$ .

$S_e = 1.1$  in the unstable regime. The initial state is chosen as the steady solution (9) with  $S_e = 1$ . For the case of  $h = 1.3$ , one can see the overdamped oscillation that converges to the steady state, but for the larger values of  $h$ , the system undergoes the oscillatory transition and the surface velocity oscillates with an saw-tooth like wave profile, namely, the gradual increase of velocity followed by a sudden drop.

The time development of the spatial variations for the state variable  $\phi$  and the velocity  $u$  are plotted in Fig.4 for  $h = 2$ . Only the positive halves ( $z > 0$ ) of the symmetric solutions are shown. One can see the high shear rate region extends gradually towards the center as  $\phi$  relaxes, then the velocity drops suddenly to a very small value when the shear rate exceeds a certain value and  $\phi$  increases rapidly. This sudden drop of velocity is due to the abrupt thickening of the fluid caused by the high shear stress. The resulting low shear rate eventually leads to the low shear stress, which in turn leads to small  $\phi$  with low viscosity, then the shear rate starts increasing again.

**Gravitational flow:** The gravitational flow in Fig.1(b) is examined within eq.(2) by adding the body force term to eq.(3) due to the gravity

$$\mathbf{g} = (g \sin \theta, 0, -g \cos \theta) \equiv (g_{\parallel}, 0, g_{\perp}) \quad (13)$$

with the boundary condition

$$u(0, t) = 0, \quad S(h, t) = 0. \quad (14)$$

The steady flow profiles  $u(z)$  are shown in Fig.5(a) for various  $g_{\parallel}$  with the depth  $h = 2$ . For a small  $g_{\parallel}$ , the profile is **nearly parabolic** as in a Newtonian fluid, but for larger  $g_{\parallel}$ , an inflection point appears in  $u(z)$ . A notable feature is that the flow velocity is slower for larger  $g_{\parallel}$ . This can be seen also in Fig.5(b), where the surface velocity  $u(h)$  is plotted against  $g_{\parallel}$ . This is a direct consequence of the shear stress thickening.

The part where  $u''(z) > 0$  corresponds to the unstable branch in the stress-shear rate curve, thus we may expect the shear thickening oscillation as in the simple shear flow. In Fig.5(c), the surface velocities are plotted as a function **of** time. One can see the oscillation as soon as the inflection point appears, but for large  $g_{\parallel}$  the oscillation overdamps due to the large viscosity<sup>24</sup>.

**Response to impact:** The athermal relaxation (6) gives the system an interesting feature in the response to an external impact. We consider the simple shear flow with the fixed lower boundary at  $z = 0$ , but the upper boundary at  $z = h$  is forced to move at the velocity  $u_0$  at  $t = 0$  (Fig.1(c)). For  $t > 0$ , the velocity of the upper wall  $U(t) \equiv u(h, t)$  is given by

$$m \frac{dU(t)}{dt} = -\eta(\phi) \left. \frac{\partial u}{\partial z} \right|_{z=h}, \quad (15)$$

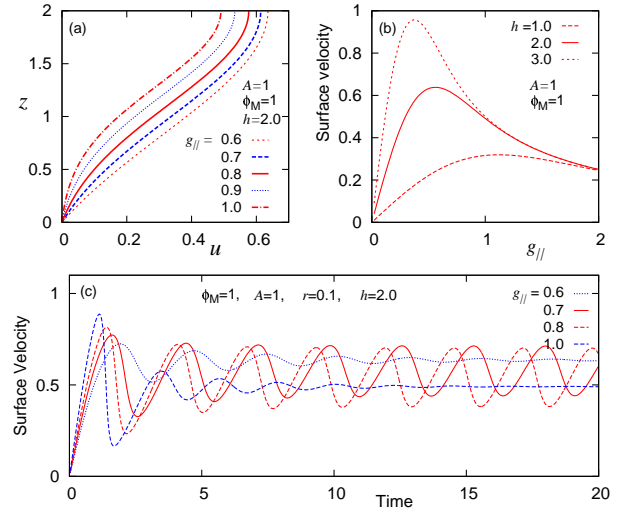


Fig. 5. Gravitational flows: (a) the flow profile of steady flow for various  $g_{\parallel}$  with  $h = 2$ . (b) the surface velocity as a function of  $g_{\parallel}$  for  $h = 1, 2$ , and 3. (c) the time-dependence of the surface velocity for  $g_{\parallel} = 0.6, 0.7, 0.8$  and 1.0 with  $h = 2$ . Other parameters are  $A = \phi_M = 1$  and  $r = 0.1$ .

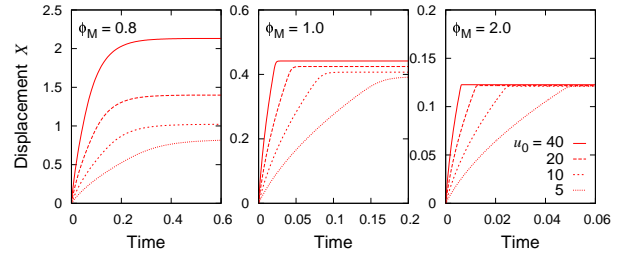


Fig. 6. The time dependence of the displacement  $X$  after the impact with the initial speed  $u_0 = 40, 20, 10$ , and 5 for the system with  $\phi_M = 0.8, 1$ , and 2. The other parameters are  $h = 2$ ,  $A = 1$ ,  $r = 0.1$ , and  $m = 1$ .

where  $m$  is the mass of the upper wall per unit length.

Fig.6 shows the displacement  $X$  of the upper wall,

$$X(t) = \int_0^t U(t') dt', \quad (16)$$

for the three cases,  $\phi_M = 0.8, 1$ , and 2 for various initial speeds. The wall decelerates rapidly as the fluid thickens due to the imposed stress, and eventually stops. For  $\phi_M = 0.8$ , the final wall distance increases as the initial speed  $u_0$ . On the other hand, for  $\phi_M = 2$ , the final displacement does not depend on  $u_0$ . This is because the fluid **gets** jammed at a certain strain as it deforms, and cannot deform further.

**Concluding remarks:** We have constructed the phenomenological model for the dilatant fluid, and **demonstrated** that the fluid may show the shear thickening oscillation. The athermal relaxation gives the fluid the property that its deformation does not depend upon the strength of the applied impact.

A couple of models have been proposed for the shear thickening fluid: the soft glassy rheology (SGR) model<sup>25</sup> and the schematic mode coupling theory (MCT).<sup>26</sup> In the SGR model, SGR is extended to describe the shear thickening by introducing the stress dependent effective temperature, which may be compared with the inverse of the state variable  $\phi$  of our model.



Fig. 7. Schematic illustration of configurations for low stress (left) and high stress(right) regime.

In the schematic MCT, the jamming transition has been examined by means of MCT incorporating the effects of shear schematically. Both are semi-empirical but deal with microscopic processes and produce the similar flow curves as Fig.2. In contrast, the present model is phenomenological one only for macroscopic description, and we study the interplay between the fluid dynamics and the shear thickening.

Although our model is phenomenological, we have the microscopic picture for the system; in the low stress regime ( $\phi \sim 0$ ), the particles are dispersed thus the medium can deform easily due to the lubrication, whereas, in the high stress regime ( $\phi \sim 1$ ), the particles form contacts and force chains to support the stress, and eventually get jammed when the packing fraction is large enough (Fig.7). With this picture, it is natural to assume that the time scale for the state change is set by the shear rate in the case where the deformation drives the configurational changes, and then the parameters  $S_0$  and  $r$  correspond to the stress and the strain, respectively, around which the neighboring granules start touching each other. In the case where the thermal relaxation also takes place, the time scale may be given by

$$1/\tau = |\dot{\gamma}|/r + 1/\tau_{th}, \quad (17)$$

where  $\tau_{th}$  is the time scale that the thermal agitation dislocates the contacts.

We have assumed that the state is determined by the shear stress, but it is instructive to consider the case where the state is determined by the shear rate. If  $\phi_*$  is a function of  $\dot{\gamma}$  instead of eq.(1), the stress-shear rate curve becomes monotonically increasing without an unstable branch, then there should be no discontinuity and hysteresis, thus no instability that leads to the oscillation. This suggests that experimentally observed discontinuous transition<sup>3</sup> and the hysteresis<sup>7</sup> can be attributed to the “shear-stress thickening” property of the medium. The direct consequence of the shear-stress thickening is seen in the gravitational slope flow, where the flux does not **increase** monotonically as the inclination angle because the fluid becomes more viscous under larger shear stress, thus it may flow slower as the slope becomes steeper.

A peculiar result of the present model is the oscillatory instability in the shear and the gravitational flow. Superficially, this might look like a stick-slip motion, but the physical origin is different; the stick-slip motion is caused by the slip weakening friction in the system driven at a constant speed through an elastic device. If the present system is driven at a constant speed, the system settles in one of the stable states for a given  $\dot{\gamma}$ . The oscillatory behavior in the present system appears under the drive with a constant shear stress, and it is a result of the coupling between the internal dynamics and the fluid dynamics. In this sense, it is also different from the oscillation in

the SGR model, where the fluid dynamics is not considered.<sup>25</sup>

Regarding the oscillations in experiments, one can easily notice the vibration around 10 Hz when pouring the cornstarch-water mixture out of a cup. In the literature, the pronounced fluctuations in the deformation rate have been reported in the shear stress controlled experiment near the critical shear rate,<sup>7,22</sup> but not many experiments have been reported yet. On the other hand, in the case of shear thinning system, much clearer oscillation have been reported in the liquid crystal systems<sup>27</sup> along with the discontinuous transition and hysteresis,<sup>28,29</sup> which may be described by the phenomenology similar to the present one.

Chaotic dynamics has been observed in dilute aqueous solutions of a surfactant in the experiment under the constant shear rate in the shear thickening regime.<sup>30,31</sup> It was interpreted as the stick-slip transition between the two states of the fluid structure, thus physical relevance to the present instability is not clear, but we also found the chaotic dynamics in the present model in the case of the constant relaxation time  $\tau$  with the large system width.

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