

AN M TIMES N CELL SPACE SURROUNDED BY TIME
INVARIANT BOUNDARIES AND TWO INHIBITION STATES
 Φ : INFORMATION SCIENCE APPROACH TO
BIOMATHEMATICS, XII

Kitagawa, Toshio

Research Institute of the Fundamental Information Science, Faculty of Science, Kyushu University

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AN $m \times n$ CELL SPACE SURROUNDED BY TIME INVARIANT BOUNDARIES AND TWO INHIBITION STATES ϕ —INFORMATION SCIENCE APPROACH TO BIOMATHEMATICS, XII

By

Tosio KITAGAWA*

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1. Introduction

This paper gives some general observations on oscillatory phenomena associated with an $m \times n$ cell space surrounded by invariant boundary periphery plus two ϕ inhibition states. In fact in our previous paper [1], we discussed such oscillatory phenomenon for the simplest case when $m = n = 2$, by means of direct enumeration of transitions among all configurations under application of local majority transformations LMT.

Although such an enumeration procedure would be too labourous and tedious to perform even for moderate values of m and n , there are some fundamental aspects of oscillatory phenomena in our general formulation, which are both simple and easily obtained with reference to our LMT.

For the sake of the definiteness let us set up the following layout concerning our configurations as shown in Figure 1.1.

$$\begin{array}{cccccccc}
 \phi & d_1 & d_2 & d_3 & \cdots & d_j & \cdots & d_n \quad \gamma \\
 a_1 & x_{11} & x_{12} & x_{13} & \cdots & x_{1j} & \cdots & x_{1n} \quad c_1 \\
 a_2 & x_{21} & x_{22} & x_{23} & \cdots & x_{2j} & \cdots & x_{2n} \quad c_2 \\
 a_3 & x_{31} & x_{32} & x_{33} & \cdots & x_{3j} & \cdots & x_{3n} \quad c_3 \\
 \vdots & \vdots & \vdots & \vdots & & \vdots & & \vdots \\
 a_i & x_{i1} & x_{i2} & x_{i3} & \cdots & x_{ij} & \cdots & x_{in} \quad c_i \\
 \vdots & \vdots & \vdots & \vdots & & \vdots & & \vdots \\
 a_m & x_{m1} & x_{m2} & x_{m3} & \cdots & x_{mj} & \cdots & x_{mn} \quad c_m \\
 \alpha & b_1 & b_2 & b_3 & \cdots & b_j & \cdots & b_n \quad \phi
 \end{array}$$

Fig. 1.1. $\phi^2 Q_{m,n}((x_{ij}); a, b, c, d; \alpha, \gamma)$.

* Research Institute of the Fundamental Information Science, Faculty of Science, Kyushu University.

An $m \times n$ cell space with configuration (x_{ij}) surrounded by four time invariant vectors $a = (a_1, a_2, \dots, a_m)$, $b = (b_1, b_2, \dots, b_n)$, $c = (c_1, c_2, \dots, c_m)$, $d = (d_1, d_2, \dots, d_n)$ and two time invariant corners α and γ with two inhibition states ϕ .

DEFINITION 1.1. A rectangular set of $(m+2) \times (n+2)$ cells as shown in Figure 1.1 is called to be an $m \times n$ cell space, denoted by $\Omega_{m,n}$, surrounded by a set of four time invariant boundary vectors a, b, c, d and two time invariant corner values α and γ with the two ϕ inhibition states when the following conditions are satisfied:

(1°) The following four boundary vectors

$$(1.01) \quad \begin{aligned} (i) \quad & a = (a_1, a_2, \dots, a_i, \dots, a_m) \\ (ii) \quad & c = (c_1, c_2, \dots, c_i, \dots, c_m) \\ (iii) \quad & b = (b_1, b_2, \dots, b_j, \dots, b_n) \\ (iv) \quad & d = (d_1, d_2, \dots, d_j, \dots, d_n) \end{aligned}$$

are time invariant under any application of LMT. Each of all the components of these four vectors is either 1 or 0.

(2°) The corners α and γ are time invariant, having either one of 1 and 0.

(3°) Two ϕ 's in the corner are inhibition state, which means a 2×2 basic cell space having ϕ element in one of cells is invariant under the application of LMT.

(4°) $(x_{i,j})$ ($i=1, 2, \dots, m; j=1, 2, \dots, n$) in the cell space $\Omega_{m,n}$ denotes any arbitrarily given configuration in an $m \times n$ cell space.

The set of $(m+2) \times (n+2)$ cells defined by these conditions is denoted by

$$(1.02) \quad \phi^2 \Omega_{m,n}((x_{i,j}); a, b, c, d; \alpha, \gamma).$$

Particularly when we are concerned with the case when some of a, b, c, d, α and γ are not specified, we shall denote each of unspecified elements by $*$. For instance

$$(1.03) \quad \phi^2 \Omega_{m,n}((x_{i,j}); *, *, c, d; *, \gamma)$$

denotes the case when two boundary vectors c and d and one corner γ are specified but a, b and α are unspecified, and similarly for

$$(1.04) \quad \phi^2 \Omega_{m,n}((x_{i,j}); a, b, *, *, \alpha, *).$$

In virtue of THEOREM 1 and its proof in Kitagawa and Yamaguchi [2], any specification of γ, c and d determines uniquely a stable configuration in $\Omega_{m,n}$ under the applications of LMT in which, in mod 2,

$$(1.05) \quad x_{i,j} = \gamma + c_i + d_j = (\gamma c d)_{i,j}, \quad \text{say, for } i=1, 2, \dots, m; j=1, 2, \dots, n.$$

Similarly any specification of α, a and b determines uniquely a stable configuration in $\Omega_{m,n}$ under the LMT in which, in mod 2,

$$(1.06) \quad x_{i,j} = \alpha + a_i + b_j = (\alpha a b)_{i,j}, \quad \text{say, for } i=1, 2, \dots, m; j=1, 2, \dots, n.$$

Now if there were no interference with the boundary vectors a, b and the corner α , that is to say, all a_i ($i=1, 2, \dots, m$) and b_j ($j=1, 2, \dots, n$) and α reduce to be ϕ , then we should reach to the configuration in the $(m+2) \times (n+2)$ cell space

$$(1.07) \quad \phi^2 \Omega_{m,n}(\gamma cd); \phi_a, \phi_b, c, d; \phi, \gamma),$$

where we put

$$(1.08) \quad \phi_a = (\phi, \phi, \dots, \phi), \quad (m\text{-dimensional})$$

$$(1.09) \quad \phi_b = (\phi, \phi, \dots, \phi), \quad (n\text{-dimensional}).$$

Similarly we could consider

$$(1.10) \quad \phi^2 \Omega_{m,n}(\alpha ab); a, b, \phi_c, \phi_d; \alpha, \phi),$$

where

$$(1.11) \quad \phi_c = (\phi, \phi, \dots, \phi), \quad (m\text{-dimensional})$$

$$(1.12) \quad \phi_d = (\phi, \phi, \dots, \phi), \quad (n\text{-dimensional}).$$

The problems of configuration changes under application of LMT are concerned with the transition phenomena among configurations for each assigned set of configuration $C(X) = (x_{ij})$ ($i = 1, 2, \dots, m; j = 1, 2, \dots, n$), $a, b, c, d, \alpha, \gamma$ and two ϕ states under applications of LMT, that is to say, with a set of configurations $C_T(X)$ induced in (1.02) by any application of LMT, which we shall denote by

$$(1.13) \quad \begin{aligned} & T\phi^2 \Omega_{m,n}(C(X); a, b, c, d; \alpha, \gamma) \\ & = \phi^2 \Omega_{m,n}(C_T(X); a, b, c, d; \alpha, \gamma). \end{aligned}$$

In this paper we shall discuss these problems in a most general formulation. It is obvious that there are two types of transition phenomena of configuration $(x_{i,j})$ under applications of LMT. The first type is concerned with transitory aspect of transition phenomena in which, starting with any assigned configuration in $\Omega_{m,n}$, we are seeking for a sequence of LMT's by which we can reach at a certain subset of all the configurations in $\Omega_{m,n}$ where we can never get out of, once we have reached any configuration belonging to the set. We shall call such a set to be a final set of all the possible configurations in (1.04) under LMT, and which will be called to be the final set of configurations in the set of a, b, c, d, α and γ , which we shall denote by $\phi^2 \Omega_{m,n}[a, b, c, d; \alpha, \gamma]$.

Now the second type of our problems is concerned with an enumeration of all elements in $\phi^2 \Omega_{m,n}[a, b, c, d; \alpha, \gamma]$ each assigned set of a, b, c, d, α and γ , and with the transition phenomena among all the configurations in $\phi^2 \Omega_{m,n}[a, b, c, d; \alpha, \gamma]$. If it so happens that, for $i = 1, 2, \dots, m; j = 1, 2, \dots, n$,

$$(1.14) \quad (\alpha ab)_{i,j} \equiv (\gamma cd)_{i,j}, \quad (\text{mod. } 2)$$

then the final set of configurations in our concern consists of just one element, that is

$$(1.15) \quad \begin{aligned} & \phi^2 \Omega_{m,n}[a, b, c, d; \alpha, \gamma] \\ & = \{\phi^2 \Omega_{m,n}((\alpha ab)_{i,j}); a, b, c, d; \alpha, \gamma\} \\ & = \{\phi^2 \Omega_{m,n}((\gamma cd)_{i,j}); a, b, c, d; \alpha, \gamma\}. \end{aligned}$$

The so-called oscillatory phenomena, which we have already verified in the $\Omega_{m,n}$, occur when

$$(1.16) \quad (\alpha ab)_{i,j} \equiv (\gamma cd)_{i,j} + 1, \pmod{2}$$

for all combinations of i and j in $i = 1, 2, \dots, m; j = 1, 2, \dots, n$.

In what follows we shall proceed to a more complicated situation from a simpler one, step by step, with the start given in Section 2.

2. The case of $\phi^2 \Omega_{m,n}(C(X); 1_a, 1_b, 0_c, 0_d; 1, 0)$

In this Section we are entirely concerned with the case when, in (1.04), we have

$$(2.01) \quad a = (1, 1, \dots, 1) = 1_a,$$

$$(2.02) \quad b = (1, 1, \dots, 1) = 1_b,$$

$$(2.03) \quad c = (0, 0, \dots, 0) = 0_c,$$

$$(2.04) \quad d = (0, 0, \dots, 0) = 0_d,$$

$$(2.05) \quad \alpha = 1,$$

$$(2.06) \quad \gamma = 0,$$

and hence with

$$(2.07) \quad \phi^2 \Omega_{m,n}(C(x); 1_a, 1_b, 0_c, 0_d; 1, 0).$$

Since we have, for $i = 1, 2, \dots, m; j = 1, 2, \dots, n$,

$$(2.08) \quad (\alpha ab)_{i,j} \equiv 1 + 1 + 1 \equiv 1, \pmod{2}$$

$$(2.09) \quad (\gamma cd)_{i,j} \equiv 0 + 0 + 0 \equiv 0, \pmod{2}.$$

The final set of configurations $\phi^2 \Omega_{m,n}[1_a, 1_b, 0_c, 0_d; 1, 0]$ contains two configurations

$$(2.10) \quad \phi^2 \Omega_{m,n}(C_0; 1_a, 1_b, 0_c, 0_d; 1, 0),$$

and

$$(2.11) \quad \phi^2 \Omega_{m,n}(C_1; 1_a, 1_b, 0_c, 0_d; 1, 0),$$

where the configuration in which all $x_{i,j}$ are equal to 0(1) is denoted by $C_0(C_1)$.

Now let us start with

LEMMA 2.1. *To any assigned configuration $C(X)$ in $\Omega_{m,n}$, there are a finite sequence of LMT denoted by $\{T_i; i = 1, 2, \dots, N_0\}$ such that*

$$(2.12) \quad \begin{aligned} & \phi^2 \Omega_{m,n}(T_{N_0} T_{N_0-1} \cdots T_2 T_1 C(X); 1_a, 1_b, 0_c, 0_d; 1, 0) \\ & = \phi^2 \Omega_{m,n}(C_0; 1_a, 1_b, 0_c, 0_d; 1, 0) \end{aligned}$$

and also a finite sequence of LMT, denoted by $\{T_{(j)}; j = 1, 2, \dots, N_1\}$ such that

$$(2.13) \quad \begin{aligned} & \phi^2 \Omega_{m,n}(T_{(N_1)} T_{(N_1-1)} \cdots T_{(2)} T_{(1)} C(X); 1_a, 1_b, 0_c, 0_d; 1, 0) \\ & = \phi^2 \Omega_{m,n}(C_1; 1_a, 1_b, 0_c, 0_d; 1, 0), \end{aligned}$$

where the non-negative integers N_0 and N_1 are depending upon the configuration $C(X)$.

Before entering into the proof, let it be noted that, since in this Section we are exclusively concerned with the cell space $\phi^2 \Omega_{m,n}(C(X); 1_a, 1_b, 0_c, 0_d; 1, 0)$, we may and we shall write

$$(2.14) \quad T_{N_0} T_{N_0-1} \cdots T_2 T_1 C(X) = C_0$$

$$(2.15) \quad T_{(N_1)} T_{(N_1-1)} \cdots T_{(2)} T_{(1)} C(X) = C_1$$

in the place of (2.12) and (2.13) respectively.

PROOF OF LEMMA 2.1. Let us begin with the first row of $\Omega_{m,n}$. Let us denote by I_1 the set of all j for which $x_{1,j} = 1$ ($1 \leq j \leq n$), that is,

$$(2.16) \quad I_1 = \{j; x_{1,j} = 1, 1 \leq j \leq n\}.$$

If I_1 is a null set, then all is right with the first row, and we shall move to the second row. If I_1 is not a null set, then there is a positive integer j_1 which is the largest integer in the set I_1 .

Now, since the cell c_{1,j_1} has one upper adjacent cell belonging either to the boundary d or to the corner γ , and also it has one right adjacent cell belonging either to the boundary c_1 or to the first row, it is always possible to find a 2×2 basic cell space in which the configuration is given by

$$(2.17) \quad \begin{pmatrix} 0 & 0 \\ x_{1,j_1} & 0 \end{pmatrix}$$

and to which an application of LMT reduces all the four elements of (2.17) into zero, while all the other elements in $\Omega_{m,n}$ remain invariant.

We can and we shall repeat such applications of LMT to the cell $c_{1,j}$ when j belongs to the set I_1 according to the descending order of j values, until we find that I_1 is reduced to a null set. Then we shall move to the second row of $\Omega_{m,n}$. Since all the elements in the first row have now zero, the similar argument can be applied to the second row, which leads us to the conclusion that there is a sequence of LMT by which all the elements of the second row in $\Omega_{m,n}$ are reduced to zero.

Proceeding in this way we shall find that there is a finite sequence $\{T_h\}$ ($h = 1, 2, \dots, N_0$) of LMT by which, starting with any assigned configuration $C(X)$ in $\Omega_{m,n}$, we obtain

$$(2.18) \quad T_{N_0} T_{N_0-1} T_{N_0-2} \cdots T_2 T_1 C(X) = C_0.$$

Similar argument holds true for the proof of an existence of a finite sequence of LMT $\{T_{(g)}\}$ ($g = 1, 2, \dots, N_1$) enunciated in the second part of LEMMA 2.1, which will start with the considerations of the m -th row and the smallest integer j_m for which $x_{m,p} = 0$ in $1 \leq p \leq n$.

In view of this Lemma, we may start with C_0 as an initial configuration. A sequence of LMT with any assigned sequence of firing points yields us another configuration, which has a certain common feature among all the possible configurations of $m \times n$ cell space. To illustrate this, it is convenient to introduce

DEFINITION 2.1. A set E of cells belonging to the cell space $\Omega_{m,n}$ is said to be left and lower inclusive, abbreviated by LLI, if, to each cell $c_{i,j}$ belonging to the set E , all the cells $\{c_{i+p,j-q}\}$ ($p=0, 1, 2, \dots, m-i$; $q=0, 1, 2, \dots, j-1$) belong to the set E .

DEFINITION 2.2. A set F of cells belonging to the cell space $\Omega_{m,n}$ is said to be right and upper inclusive, abbreviated by RUI, if, to each cell $c_{i,j}$ belonging to the set F , all the cells $\{c_{i-p,j+q}\}$ ($p=0, 1, 2, \dots, i-1$; $q=0, 1, 2, \dots, n-j$) belong to the set F .

We observe

COROLLARY 2.1. A set of cells E is LLI if and only if the complementary set $\Omega_{m,n}-E$ is RUI.

EXAMPLE 2.1.

$$\begin{pmatrix} \phi & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 & 0 & 1 & 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 & 1 & 1 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & \phi \end{pmatrix}$$

Fig. 3.2, (a). Non-LLI set and non-RUI set.

$$\begin{pmatrix} \phi & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 & 1 & 1 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 & 1 & 1 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & \phi \end{pmatrix}$$

Fig. 3.2, (b). LLI set E and $C[E]$ associated with E .

The set of all the LLI sets in $\Omega_{m,n}$, which will be denoted by $\mathfrak{L}_{m,n}$, constitutes a lattice, and similarly for the set of all the RUI set in $\Omega_{m,n}$ which will be denoted by $\mathfrak{R}_{m,n}$.

DEFINITION 2.3. For each set E belonging to $\mathfrak{L}_{m,n}$, the configuration $C[E]$ associated with E is defined by

$$(2.19) \quad \begin{aligned} x_{i,j} &= 1 && \text{if the cell } c_{i,j} \in E \\ &= 0 && \text{if the cell } c_{i,j} \in \Omega_{m,n} - E \end{aligned}$$

The situation which we have now presented can be illustrated by the following Example.

We observe

LEMMA 2.2. Any application of LMT in our cell space to any given configuration $C[E]$ associated with a LLI set E , gives a configuration $C[E']$ associated with a LLI set E' . Similarly for RUI.

PROOF. Any application of LMT gives a substantial change of configuration

when in the corresponding 2×2 basic cell space we have

$$(2.20) \quad x_{i,j} + x_{i,j+1} + x_{i+1,j} + x_{i+1,j+1} \equiv 1 \pmod{2}.$$

In view of the assumption that E is a LLI set, all the possible configurations in the basic 2×2 cell space are either of the following four configurations.

$$(2.21) \quad \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \quad \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}, \quad \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix},$$

each of which is transformed to each of the following ones respectively

$$(2.22) \quad \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}, \quad \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}, \quad \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}, \quad \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

by the application of LMT. By each of these local changes in the basic cell, $C(E)$ is transformed to another configuration $C(E')$ where E' is again a LLI set. This completes the proof of the first part of LEMMA 2.2. Similarly for the second part by means of the notion of RUI sets, which completes the whole proof of LEMMA 2.2.

In view of these Lemmas and their proofs it is immediate to observe

LEMMA 2.3. (1°) *The set of all LLI sets (and hence RUI sets) in $\Omega_{m,n}$ constitutes a lattice with the unity $\Omega_{m,n}$ and zero element Φ according to the semi-ordered relation included by the set inclusion relation.*

(2°) *To any pair of two configurations $C[E]$ and $C[F]$ associated with to LLI sets E and F respectively such that $E \subset F$ in the lattice defined in (1°), there is a finite sequence of LMT's $\{T_i\}$ ($i=1, 2, \dots, N_0$) such that*

$$(2.23) \quad \begin{aligned} & (i) \quad T_i T_{i-1} \dots T_2 T_1 E = E_i \quad (i=1, 2, \dots, N_0) \\ & (ii) \quad E_{N_0} = F \\ & (iii) \quad E \subset E_1 \subset E_2 \dots E_{N_0-1} \subset E_{N_0}. \end{aligned}$$

(3°) *To any pair of two configurations $C[E]$ and $C[F]$ associated with two RUI sets E and F respectively such that $E \supset F$ in the lattice defined in (1°), there is a finite sequence of LMT's $\{T_{(j)}\}$ ($j=1, 2, \dots, N_1$) such that*

$$(2.24) \quad \begin{aligned} & (i) \quad T_{(j)} T_{(j-1)} \dots T_{(2)} T_{(1)} E = E_j \quad (j=1, 2, \dots, N_1) \\ & (ii) \quad E_{N_1} = F \\ & (iii) \quad E \supset E_1 \supset E_2 \supset \dots \supset E_{N_1-1} \supset E_{N_1}. \end{aligned}$$

PROOF. Since (1°) is obvious and (3°) is similar to (2°), it will be sufficient to show (2°). Now let us denote by k the number of cells in the difference $F-E$. The proof will be done by induction as to k . First let $k=1$. Let us denote the cell belonging to $F-E$ by $c_{i,j}$. Then the 2×2 basic cell space consisting of $c_{i,j-1}$, $c_{i,j}$, $c_{i+1,j-1}$ and $c_{i+1,j}$ has the configuration

$$(2.25) \quad \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}.$$

In the consequence there is a LMT having the firing point in this 2×2 basic cell space which transforms (2.25) into

$$(2.26) \quad \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

and hence transforms the configuration $C[E]$ into $C[F]$.

Now let us assume that the assertion in (2°) is valid for $k=h$. Let us prove that it is valid for $k=h+1$. Since both E and F are LLI set, there is at least one cell $c_{p,q}$ belonging to $F-E$ such that the 2×2 basic cell space consisting of $c_{p,q-1}$, $c_{p,q}$, $c_{p+1,q-1}$ and $c_{p+1,q}$ has the configuration as in (2.24), because of the fact that each of these cells belongs either to the set E or to the a , b boundaries and the corner α , whose value is equal to 1. The application of LMT at this 2×2 basic cell space reduces the number $h+1$ of the set $F-E$ to the number h of the transformed set for which the assertion holds true. This completes the induction and hence the proof of (2°).

It is convenient to introduce

DEFINITION 2.3. (a) *The set of all LLI sets in $\Omega_{m,n}$ is called to be the LLI family and denoted by $(\mathfrak{L}\mathfrak{L})_{m,n}$.*

(b) *The set of all RUI sets in $\Omega_{m,n}$ is called to be the RUI family and denoted by $(\mathfrak{R}\mathfrak{U})_{m,n}$.*

In combination of the three Lemmas and Definitions in this Section, we are now able to make clear the whole transition features of configurations in our particular cell space. In fact we have

THEOREM 2.1. *In a cell space $\phi^2\Omega_{m,n}(C(X); 1_a, 1_b, 0_c, 0_d; 1, 0)$ we have the following assertions:*

(1°) (Transitory aspect) *To each pair of any assigned configuration $C(X)$ and any assigned configuration $C[E](\overline{C[F]})$ which is associated with a LLI set E (a RUI set F) there exists a finite sequence of LMT $\{T_i\}$ ($\{T_{(j)}\}$) whose sequential applications in this order transforms $C(X)$ into $C[E](\overline{C[F]})$.*

(2°) (The final set of configurations) *$\phi^2\Omega_{m,n}(1_a, 1_b, 0_c, 0_d; 1, 0)$ is equal to the set of all the configurations $C[E](\overline{C[F]})$ when E runs through $(\mathfrak{L}\mathfrak{L})_{m,n}$ (F runs through $(\mathfrak{R}\mathfrak{U})_{m,n}$), that is,*

$$(2.27) \quad \begin{aligned} \phi^2\Omega_{m,n}(1_a, 1_b, 0_c, 0_d; 1, 0) &= [C[E]; E \in (\mathfrak{L}\mathfrak{L})_{m,n}] \\ &= [C[F]; F \in (\mathfrak{R}\mathfrak{U})_{m,n}]. \end{aligned}$$

(3°) *Once a configuration $C(X)$ coincides with a configuration $C[E](\overline{C[F]})$ corresponding to a LLI set E (an RUI set F), then any application of LMT can only give another configuration $C[E'](\overline{C[F']})$ corresponding to a LLI set E' (a RUI set F').*

3. $\phi^2\Omega_{m,n}$ cell space with conjugate configuration boundaries and corners

Let us consider a cell space $\phi^2\Omega_{m,n}((\alpha ab); a, b, *, *; \alpha, *)$, in which the configuration $(x_{i,j})$ in $\Omega_{m,n}$ is given by

$$(3.01) \quad x_{i,j} = \alpha + a_i + b_j, \quad (\text{mod. } 2) \quad (i=1, 2, \dots, m; j=1, 2, \dots, n),$$

with an assigned triple of α , a and b , while the boundary vectors c , d and the cor-

ner γ are not specified, and also let us consider a cell space $\phi^2 \Omega_{m,n}(\gamma cd); *, *, c, d; 0, \gamma$ in which the configuration $(y_{i,j})$ in $\Omega_{m,n}$ is given by

$$(3.02) \quad y_{i,j} = \gamma + c_i + d_j, \quad (\text{mod. } 2), \quad (i = 1, 2, \dots, m; j = 1, 2, \dots, n)$$

in a similar way. In this Section we are interested with the case when there hold

$$(3.03) \quad x_{i,j} + 1 \equiv y_{i,j}, \quad (\text{mod. } 2),$$

for all i and j in $\Omega_{m,n}$.

For this purpose let us introduce a set of conjugate configuration boundaries and corners in which there hold

$$(3.04) \quad c_i \equiv a_i + 1$$

$$(3.05) \quad d_j \equiv b_j + 1 \quad (\text{mod. } 2)$$

$$(3.06) \quad \gamma \equiv \alpha + 1$$

for $i = 1, 2, \dots, m$ and $j = 1, 2, \dots, n$. That is to say, we are concerned with a cell space

$$(3.07) \quad \phi^2 \Omega_{m,n}(C(X); a, b, \bar{a}, \bar{b}; \alpha, \bar{\alpha}),$$

where bar notations mean the conjugate vector and conjugate value, and we are interested with the behaviour of configuration $C(X)$ in $\Omega_{m,n}$. There is no stable configuration in (3.07), as we can easily observe from the conditions (3.04)–(3.06). It is also immediate to observe

COROLLARY 3.1. $\phi^2 \Omega_{m,n}(C(X); 1_a, 1_b, 0_c, 0_d; 1, 0)$ has a set of conjugate configuration boundaries and corners.

It may be interesting to establish some results regarding oscillatory phenomena in our $\phi^2 \Omega_{m,n}(C(X); a, b, \bar{a}, \bar{b}; \alpha, \bar{\alpha})$ which can be recognized as generalizations of the results obtained in Section 2. However such an analogue is not so simple as one might imagine at its immediate conjecture. Let us explain the situation by the following

EXAMPLE 3.1. Let us consider the case when $m = 8, n = 9$ and

$$a = (1, 1, 0, 0, 1, 0, 0, 1)$$

$$b = (1, 0, 0, 0, 1, 1, 0, 0, 1)$$

$$c = (0, 0, 1, 1, 0, 1, 1, 0) = \bar{a}$$

$$d = (0, 1, 1, 1, 0, 0, 1, 1, 0) = \bar{b}$$

$$\alpha = 1, \gamma = 0 = \bar{\alpha}.$$

The configuration $C[(\alpha ab)]$ is not stable at the upper and right corner as shown in Figure 3.1, (a) and the configuration $C[(\gamma cd)]$ is not stable at the lower and left corner as shown in Figure 3.1, (b).

ϕ	0	1	1	1	0	0	1	1	0	0
1	1	0	0	0	1	1	0	0	1	0
1	1	0	0	0	1	1	0	0	1	0
0	0	1	1	1	0	0	1	1	0	1
0	0	1	1	1	0	0	1	1	0	1
1	1	0	0	0	1	1	0	0	1	0
0	0	1	1	1	0	0	1	1	0	1
0	0	1	1	1	0	0	1	1	0	1
1	1	0	0	0	1	1	0	0	1	0
1	1	0	0	0	1	1	0	0	1	ϕ

Fig. 3.1, (a). Configuration $C[(\alpha ab)]$.

ϕ	0	1	1	1	0	0	1	1	0	0
1	0	1	1	1	0	0	1	1	0	0
1	0	1	1	1	0	0	1	1	0	0
0	1	0	0	0	1	1	0	0	1	1
0	1	0	0	0	1	1	0	0	1	1
1	0	1	1	1	0	0	1	1	0	0
0	1	0	0	0	1	1	0	0	1	1
0	1	0	0	0	1	1	0	0	1	1
1	0	1	1	1	0	0	1	1	0	0
1	1	0	0	0	1	1	0	0	1	ϕ

Fig. 3.1, (b). Configuration $C[(\gamma cd)]$.

ϕ	0	1	1	1	0	0	1	1	0	0
1	0	1	1	1	0	0	1	1	0	0
1	1	1	1	1	0	0	1	1	0	0
0	0	1	0	0	1	1	0	0	1	1
0	0	1	1	1	0	0	1	0	1	1
1	1	0	0	0	1	1	0	1	0	0
0	0	1	1	1	0	0	1	0	1	1
0	0	1	1	1	0	0	1	0	1	1
1	1	0	0	0	1	1	0	0	0	0
1	1	0	0	0	1	1	0	0	1	ϕ

Fig. 3.1, (c). $\phi^2 \Omega_{8,9}(C(X_1); a, b, \bar{a}, \bar{b}; 1, 0)$ Mixed configuration of (αab) and (γcd) according to a LLI set E shown by dotted boundary.

Let us consider a LLI set E (and hence RUI set $F = \Omega_{8,9} - E$) in which the configuration is coincident with (αab) and elsewhere it is coincident with (γcd) , which has a conjugate value of (αab) in each corresponding cell. An example is shown in Figure 3.1, (c).

Now the difficulty comes from the specific property of local majority transformation LMT itself. By a formal application of LMT, we can not reach neither to $C(\alpha ab)$ nor to $C(\gamma cd)$ in $\Omega_{m,n}$, from the configuration given in Figure 3.1, (c), which we denote by $\phi^2 \Omega_{8,9}(C(X_1); a, b, \bar{a}, \bar{b}; 1, 0)$, unless we would introduce a certain kind of interpretation about the roles of boundary vectors and corners. In fact it is important to observe that the time invariance of boundaries and corners should be interpreted to penetrate, in a certain sense, into the cell space $\Omega_{m,n}$.

Our interpretation of application of LMT to any assigned configuration (3.07) is based upon the following notions given by the following Definitions.

DEFINITION 3.1. *To each assigned configuration $C(X)$ in (3.07), the difference configuration of $C(X)$ with respect to $C(\alpha ab)$ is defined by the configuration $(y_{i,j})$ ($i = 1, 2, \dots, m; j = 1, 2, \dots, n$) where*

$$(3.08) \quad y_{i,j} \equiv x_{i,j} - (\alpha + a_i + b_j) \pmod{2}$$

and is denoted by

$$(3.09) \quad C(X; \alpha \beta \gamma) = C(X) - C(\alpha ab).$$

By virtue of this Definition we now introduce

DEFINITION 3.2. *The (Boolean) sum of two $\phi^2 \Omega_{m,n}$ cell spaces is defined by*

$$(3.10) \quad \begin{aligned} & \sum_{i=1}^2 \phi^2 \Omega_{m,n}(C(X_i); a_i, b_i, c_i, d_i; \alpha_i, \gamma_i) \\ &= \phi^2 \Omega_{m,n}(C(X_1 + X_2); a_1 + a_2, b_1 + b_2, c_1 + c_2, d_1 + d_2, \alpha_1 + \alpha_2, \gamma_1 + \gamma_2), \end{aligned}$$

where we have put

$$(3.11) \quad \begin{aligned} C(X_1 + X_2) &= C(X_1) + C(X_2) \\ &= (x_{i,j}^{(1)}) + (x_{i,j}^{(2)}) \\ &= (x_{i,j}^{(1)} + x_{i,j}^{(2)}) \end{aligned}$$

as usual matrix Boolean sum.

We note

COROLLARY 3.2. *Any $\phi^2 \Omega_{m,n}$ cell space with the time invariant conjugate boundaries and corners with $\alpha = 1$ can be considered to be the sum of two $\phi^2 \Omega_{m,n}$ cell spaces in the following form*

$$(3.12) \quad \begin{aligned} & \phi^2 \Omega_{m,n}(C(X); a, b, \bar{a}, \bar{b}; 1, 0) \\ &= \phi^2 \Omega_{m,n}(C[(\overline{\alpha ab})]; \bar{a}, \bar{b}, \bar{a}, \bar{b}; 0, 0) \\ & \quad + \phi^2 \Omega_{m,n}(C(X; \overline{\alpha ab}); 1_a, 1_b, 0_c, 0_d; 1, 0). \end{aligned}$$

This is immediate from the following relations:

$$\begin{aligned}
 (3.13) \quad & a = \bar{a} + 1_a, \quad b = \bar{b} + 1_b, \\
 & c = c + 0_c = \bar{a} + 0_c, \quad d = d + 0_d = b + 0_c, \\
 & \alpha = 1 = \bar{\alpha} + 1, \quad \bar{\alpha} = \bar{\alpha} + 0,
 \end{aligned}$$

and

$$\begin{aligned}
 (3.14) \quad & C[(\overline{\alpha ab})] = C[(\bar{\alpha} \bar{a} \bar{b})] \\
 & = (\bar{\alpha} + \bar{a}_i + \bar{b}_j) \\
 & = ((\alpha + 1) + (a_i + 1) + (b_j + 1)) \\
 & = (\alpha + a_i + b_j + 1) \\
 & C(X; \overline{\alpha ab}) = (x_{i,j} - (\alpha + a_i + b_j + 1)).
 \end{aligned}$$

The interpretations of applications of LMT in $\phi^2 \Omega_{m,n}$ cell space with the time invariant conjugate boundaries and corners is due to the following

ASSUMPTION I. Any application of LMT in a cell space $\phi^2 \Omega_{m,n}$ defined by the left hand side of (3.12) is equal to the sum of the results of application of LMT to each summand of the right-hand side of (3.12):

$$\begin{aligned}
 (3.16) \quad & L\phi^2 \Omega_{m,n}(C(X); a, b, \bar{a}, \bar{b}; 1, 0) \\
 & = L\phi^2 \Omega_{m,n}(C[(\overline{\alpha ab})]; \bar{a}, \bar{b}, \bar{a}, \bar{b}; 0, 0) \\
 & \quad + L\phi^2 \Omega_{m,n}(C(X; \overline{\alpha ab}); 1_a, 1_b, 0_c, 0_d; 1, 0).
 \end{aligned}$$

In view of the fact that

$$\begin{aligned}
 (3.17) \quad & L\phi^2 \Omega_{m,n}(C[(\overline{\alpha ab})]; \bar{a}, \bar{b}, \bar{a}, \bar{b}; 0, 0) \\
 & = \phi^2 \Omega_{m,n}(C[(\overline{\alpha ab})]; \bar{a}, \bar{b}, \bar{a}, \bar{b}; 0, 0)
 \end{aligned}$$

that is, stable in $\phi^2 \Omega_{m,n}$, the whole problem is now reduced to the particular case discussed in Section 2.

ϕ	0	1	1	1	0	0	1	1	0	0
1	0	0	0	0	0	0	0	0	0	0
1	1	1	0	0	0	0	0	0	0	0
0	1	0	1	1	0	0	0	1	0	1
0	1	0	0	0	1	1	0	0	0	1
1	0	1	0	0	0	0	1	1	0	0
0	0	0	1	0	0	1	0	1	0	1
0	0	0	0	1	1	0	1	0	0	1
1	0	0	0	0	0	1	0	0	0	0
1	1	0	0	0	1	1	0	0	1	ϕ

Fig. 3.2. $\phi^2 \Omega_{8,8}(C(X); a, b, \bar{a}, \bar{b}; 1, 0)$.

where the second summand in the right-hand side is shown in Figure 3.5.

ϕ	0	0	0	0	0	0	0	0	0	0
1	0	1	1	1	0	0	1	1	0	0
1	1	0	1	1	0	0	1	1	0	0
1	0	0	1	1	1	1	0	1	0	0
1	0	0	0	0	0	0	0	0	1	0
1	0	0	1	1	0	0	0	0	0	0
1	1	0	1	0	1	0	0	1	1	0
1	1	0	0	1	0	1	1	0	1	0
1	0	0	1	1	0	1	1	1	1	0
1	1	1	1	1	1	1	1	1	1	ϕ

Fig. 3.5. $\phi^2\Omega_{8,9}(C(X_2; \overline{\alpha ab}); 1_a, 1_b, 0_c, 0_d; 1, 0)$.

After the consideration of implications of the time invariant properties of boundaries and corners as illustrated in EXAMPLE 3.1, it is convenient to introduce

DEFINITION 3.3. A configuration $C(Z)$ in a cell space $\phi^2\Omega_{m,n}(C(Z); a, b, \bar{a}, \bar{b}; 1, 0)$ is said to be associated with a LLI set E if E is a LLI set in $\Omega_{m,n}$ and, for $i=1, 2, \dots, m$ and $j=1, 2, \dots, n$, we have

$$(3.21) \quad z_{i,j} = \bar{\alpha} + \bar{a}_i + \bar{b}_j + e_{i,j},$$

where

$$(3.22) \quad e_{i,j} = \begin{cases} 1 & \text{if the cell } c_{i,j} \in E \\ 0 & \text{if the cell } c_{i,j} \notin E, \end{cases}$$

that is to say, we have

$$(3.23) \quad C(Z) = C(\overline{\alpha ab}) + C[E]$$

and

$$(3.24) \quad \begin{aligned} & \phi^2\Omega_{m,n}(C(Z); a, b, \bar{a}, \bar{b}; 1, 0) \\ &= \phi^2\Omega_{m,n}(C[\overline{\alpha ab}]; \bar{a}, \bar{b}, \bar{a}, \bar{b}; 0, 0) \\ & \quad + \phi^2\Omega_{m,n}(C[E]; 1_a, 1_b, 0_c, 0_d; 1, 0). \end{aligned}$$

We now enunciate

THEOREM 3.1. In the set of all the configurations in $\phi^2\Omega_{m,n}[a, b, \bar{a}, \bar{b}; 1, 0]$ for any assigned pair of a and b , we have the following assertions:

(1°) (Transitory aspect) To each pair of any assigned configuration $C(X)$ in $\Omega_{m,n}$ and any assigned LLI set E , there exists a finite sequence of LMT $\{T_i\}$ ($i=1, 2, \dots, N_0$) such that the repeated applications of the sequence in this order give us

$$\begin{aligned}
 (3.25) \quad & \left(\prod_{i=N_0}^1 T_i \right) \phi^2 \Omega_{m,n}(C(Z); a, b, \bar{a}, \bar{b}; 1, 0) \\
 & = \phi^2 \Omega_{m,n}(C[\overline{\alpha ab}] + C[E]; a, b, \bar{a}, \bar{b}; 1, 0)
 \end{aligned}$$

(2°) (Final aspect) $\phi^2 \mathfrak{E}_{m,n}(\overline{\alpha ab})$ is the final set of configurations in $\phi^2 \Omega_{m,n}[(a, b, \bar{a}, \bar{b}; 1, 0)]$ in the sense that, besides the assertion (1°), there holds the assertion that any application of LMT to any configuration belonging to $\phi^2 \mathfrak{E}_{m,n}(\overline{\alpha ab})$ can only give a configuration belonging to $\phi^2 \mathfrak{E}_{m,n}(\overline{\alpha ab})$.

(3°) (Oscillatory aspect) To each pair of any assigned two configurations belonging to $\phi^2 \mathfrak{E}_{m,n}(\overline{\alpha ab})$ there exists a finite sequence of LMT which transforms the one into the other.

THEOREM 3.1 is a generalization of THEOREM 2.1 which corresponds to the case when $a = 1_a$ and $b = 1_b$. The proof of THEOREM 3.1 is immediate from that of THEOREM 2.1. The enunciation of THEOREM 2.1 can be reduced to that similar to THEOREM 3.1.

4. $\phi^2 \Omega_{m,n}$ cell space under general boundaries

We now proceed to consider a cell space $\phi^2 \Omega_{m,n}(C(X); a, b, c, d; 1, 0)$ without any connection among a, b, c , and d . In view of the decomposition principle introduced in Section 4, we have the decomposition

$$\begin{aligned}
 (4.01) \quad & \phi^2 \Omega_{m,n}(C(X); a, b, c, d; 1, 0) \\
 & = \phi^2 \Omega_{m,n}(\overline{\alpha ab}); \bar{a}, \bar{b}, c, d; 0, 0) \\
 & \quad + \phi^2 \Omega_{m,n}(C(X; \overline{\alpha ab}); 1_a, 1_b, 0_c, 0_d; 1, 0).
 \end{aligned}$$

Now it is noted that the first summand in the right-hand side of (4.01) is not stable in general, because we can not expect to have the relation $\bar{a} = c, \bar{b} = d$ under our general boundary configuration. In order to have a quick understanding of the behaviour induced by applications of LMT to the first summand of (4.01), it is convenient to observe an illustrative example.

EXAMPLE 4.1. Let us consider $\phi^2 \Omega_{8,9}(\overline{\alpha ab}); \bar{a}, \bar{b}, c, d; 0, 0)$, where

$$\begin{aligned}
 (4.02) \quad & \bar{a} = (1, 1, 0, 0, 1, 0, 0, 0) \\
 & \bar{b} = (1, 0, 1, 0, 1, 1, 1, 0, 0) \\
 & c = (1, 1, 1, 0, 0, 0, 0, 1) \\
 & d = (0, 1, 1, 1, 0, 0, 0, 1, 0) \\
 & \alpha = 0, \quad \gamma = 0.
 \end{aligned}$$

In Figure 4.1, (a), the configuration $C(\overline{\alpha ab})$ is given, which has so many unstable 2×2 basic cell spaces along the upper and along the right boundaries. In Figure 4.1, (b), the configuration $C(\overline{\gamma cd})$ is given, which has now so many unstable 2×2 basic cell spaces along the lower and along the left boundaries. In $\Omega_{m,n}$ the values of some cells change while those of other cells remain unchanged in both of two

ϕ	0	1	1	1	0	0	0	1	0	0
1	0	1	0	1	0	0	0	1	1	0
1	0	1	0	1	0	0	0	1	1	1
0	1	0	1	0	1	1	1	0	0	1
0	1	0	1	0	1	1	1	0	0	0
1	0	1	0	1	0	0	0	1	1	0
0	1	0	1	0	1	1	1	0	0	0
0	1	0	1	0	1	1	1	0	0	0
0	1	0	1	0	1	1	1	0	0	1
0	1	0	1	0	1	1	1	0	0	ϕ

Fig. 4.1, (a). $\phi^2\Omega_{8,9}(\overline{\alpha ab}) ; \bar{a}, \bar{b}, c, d ; 0, 0$.

ϕ	0	1	1	1	0	0	0	1	0	0
1	1	0	0	0	1	1	1	0	1	1
1	1	0	0	0	1	1	1	0	1	1
0	1	0	0	0	1	1	1	0	1	1
0	0	1	1	1	0	0	0	1	0	0
1	0	1	1	1	0	0	0	1	0	0
0	0	1	1	1	0	0	0	1	0	0
0	0	1	1	1	0	0	0	1	0	0
0	1	0	0	0	1	1	1	0	1	1
0	1	0	1	0	1	1	1	0	0	ϕ

Fig. 4.1, (b). $\phi^2\Omega_{8,9}(\overline{\gamma cd}) ; \bar{a}, \bar{b}, c, d ; 0, 0$.

configurations $C(\overline{\alpha ab})$ and $C(\overline{\gamma cd})$. In fact the value of a cell $c_{i,j}$ is unchanged, if and only if there hold the equations

$$(4.03) \quad \bar{a}_i + \bar{b}_j \equiv c_i + d_j \pmod{2}.$$

The condition given in (4.03) for all possible mn combinations i and j gives us a division of the total $\Omega_{m,n}$ space into the sum of invariant area I and alternating

ϕ	0	1	1	1	0	0	0	1	0	0
1										1
1										1
0										1
0										0
1										0
0										0
0										0
0										1
0	1	0	1	0	1	1	1	0	0	ϕ

Fig. 4.2. $I\phi^2\Omega_{8,9}[a, b, c, d; 1, 0]$ shown by dotted domain.

area A , where I consists of rectangular cell subspaces in which the value of each cell is constant, while in $A = \Omega_{m,n} - I$, each cell has the possibility of taking both of two values 1 and 0. The situation is illustrated by Figure 4.2. More accurately

$$\begin{aligned}
 I &= I\phi^2\Omega_{m,n}[a, b, c, d; 1, 0] \\
 A &= A\phi^2\Omega_{m,n}[a, b, c, d; 1, 0] \\
 &= \phi^2\Omega_{m,n}[a, b, c, d; 1, 0] - I\phi^2\Omega_{m,n}[a, b, c, d; 1, 0].
 \end{aligned}$$

We introduce

DEFINITION 4.1. A cell $c_{i,j}$ in a cell space $\phi^2\Omega_{m,n}(C(X); a, b, c, d; 1, 0)$ is said to belong to the invariant class I or to the alternating class A respectively according to the situation

$$(4.04) \quad a_i + b_j \equiv c_i + d_j \pmod{2}$$

or

$$(4.05) \quad a_i + b_j \equiv c_i + d_j + 1 \pmod{2}.$$

It is immediate to observe

LEMMA 4.1. In a cell space $\phi^2\Omega_{m,n}(C(X); a, b, c, d; 1, 0)$, there is a pair of partitions such that

$$(4.06) \quad m = m_1 + m_2 + \cdots + m_k$$

$$(4.07) \quad n = n_1 + n_2 + \cdots + n_l$$

with positive integers m_i and n_j , $1 \leq i \leq k$, $1 \leq j \leq l$, where k and l are subject to $1 \leq k \leq m$, $1 \leq l \leq n$. In correspondence with the pair of partitions given by (4.06) and (4.07) the whole $\Omega_{m,n}$ cell space is divided into kl subspaces, $\{S(m_{i,j})\}$ ($i = 1, 2, \dots, k$;

$j=1, 2, \dots, l)$ which are classified into two classes I and A given in Definition 4.1. The two classes occur alternatively in $\{S(m_i, n_j)\}$ (See Figure 4.4).

ϕ	n_1	n_2	n_3	n_4	n_5	n_l	γ
m_1	I	A	I	A	I	A	
m_2	A	I	A	I	A	I	
m_3	I	A	I	A	I	A	
m_4	A	I	A	I	A	I	
m_k	I	A	I	A	I	A	
α							ϕ

Fig. 4.4.

DEFINITION 4.2. The decomposition of $\Omega_{m,n}$ into a family of $\{S(m_i, n_j)\}$ ($i=1, 2, \dots, k; j=1, 2, \dots, l$) is said to be an I – A pattern inherited in the boundary configurations of $\phi^2\Omega_{m,n}(C(X); a, b, c, d; 1, 0)$.

With these preparations we can now reach the observations given by

THEOREM 4.1. In a cell space $\phi^2\Omega_{m,n}(C(X); a, b, c, d; 1, 0)$, the whole $\Omega_{m,n}$ space can be divided into the I – A pattern inherited in the boundary configurations of $\phi^2\Omega_{m,n}(C(X); a, b, c, d; 1, 0)$. Any application of LMT in each subspace belonging to the invariant class does invoke no change at all, while in each subspace belonging to the alternating class it yields the change induced by the second term of the right-hand side of (4.01), which is discussed in Section 2.

5. Summary and remarks

We introduce a certain cell space $\phi^2\Omega_{m,n}(C(X); a, b, c, d; \alpha, \gamma)$ with the invariant boundary vectors a, b, c, d and the invariant corners α, γ with two inhibition ϕ states in the opposite corners.

Starting in Section 2 with the particular case in which $a=(1, 1, \dots, 1)$, (m -dimension) $b=(1, 1, \dots, 1)$ (n -dimensional), $c=\bar{a}$, $d=\bar{b}$, $\alpha=1$, $\gamma=0$, in Section 3 we proceed to the so-called conjugate boundary configurations in which $c=\bar{a}$, $d=\bar{b}$, and finally in Section 4 we reach to the most general boundary configurations. What we establish in all of these Sections is to show that transitory aspects and final state aspects are common to those given in Section 2, where the notions of LLI sets and RUI sets play an important role.

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