

## ON A WALD'S EQUATION AND AVERAGE SAMPLE NUMBER IN A SEQUENTIAL SIGNAL DETECTION

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# ON A WALD'S EQUATION AND AVERAGE SAMPLE NUMBER IN A SEQUENTIAL SIGNAL DETECTION

By

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## § 1. Summary.

It is shown that in detecting sequentially a deterministic signal  $\phi(t)$  in white noise  $\eta(t)$  a similar identity (iii) in theorem 2.1, to the Wald's holds concerning a stopping time  $\tau$  determined by making use of a likelihood ratio. It is also shown that  $\tau$  has finite moments of any order under quite weak conditions over the signal. The exact A. S. N.  $E\{\tau\}$  in a constant signal case has been obtained and given by (2, 8).

It is also considered a detection problem of a constant signal  $\phi(t) \equiv \alpha$  in a coloured noise based on a sub-optimal statistic which become optimal when the noise were white. Similar properties of a stopping time  $\tau$  to those in the white noise case have been obtained in theorem 3.1.

## § 2. Detection of a deterministic signal in a white noise.

We consider the following detection problem of a signal  $\phi(t)$  in the white noise  $\eta(t)$ ;

$$\begin{aligned} H_0; \quad x(t) &= W(t) \\ H_1; \quad x(t) &= m(t) + W(t), \end{aligned} \tag{2.1}$$

where  $m(t) = \int_0^t \phi(s) ds$  is the integrated signal and  $\{W(t), 0 \leq t < \infty\}$  is the Wiener process which is considered to be the integrated form of the white noise  $\eta(t)$ .

By  $H_0$  we mean that there is no signal in the (integrated) observation  $x(t)$  whose distribution is induced from the Wiener measure  $P_0$  and by  $H_1$  the observation  $x(t)$  is the sum of the signal  $m(t)$  and the noise  $W(t)$  whose distribution is induced by  $P_1$ , i.e. a shift of  $P_0$  by  $m(\cdot)$ .

In order for the detection problem (2.1) to be non-singular, we assume that  $\phi(\cdot)$  is square integrable on each finite interval  $[0, t]$ ,  $0 \leq t < \infty$ .

Let us put

$$V(t) = \int_0^t |\phi(s)|^2 ds < \infty. \tag{2.2}$$

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Let  $\mathfrak{B}_t$ ,  $0 \leq t < \infty$ , be the  $\sigma$ -field generated by the observation  $\{x(s), 0 \leq s \leq t\}$  and  $P_{it}$ ,  $i=0, 1$ , restrictions of  $P_i$ ,  $i=0, 1$ , to  $\mathfrak{B}_t$  respectively.

$P_{0t}$  and  $P_{1t}$  are equivalent for each  $t$ , and the logarithm of the likelihood ratio  $L(x; t)$  of  $P_{1t}$  with respect to  $P_{0t}$  is given (See [5], [6]) by

$$L(x; t) = \int_0^t \phi(s) dx(s) - \frac{1}{2} V(t). \quad (2.3)$$

The statistic  $L(x; t)$  is optimal in the sense that it will give the most powerful critical region in this detection problem for testing  $H_0$  vs.  $H_1$  based on  $\{x(s), 0 \leq s \leq t\}$ , (See [3]).

At first we set error probabilities to be equal to the prescribed value  $\gamma$ , ( $0 < \gamma \leq 1/2$ ), that is,

$$P(\text{to accept } H_1 | H_0) = P(\text{to accept } H_0 | H_1) = \gamma. \quad (2.4)$$

We define a stopping time  $\tau$  by

$$\tau = \inf \{t > 0; L(x; t) \leq -\lambda_0 \text{ or } L(x; t) \geq \lambda_1\}, \quad (2.5)$$

where  $\lambda_0$  and  $\lambda_1$  are positive constants such that our following decision rule satisfies (2.4).

Our decision rule based on the observations  $\{x(s), 0 \leq s \leq t\}$  will be formulated as follows; When  $L(x; \tau) = \lambda_1$ , (or  $-\lambda_0$ ), we stop sampling at  $t = \tau$  and decide  $H_1$ , (or  $H_0$ ), to be true, while as long as  $-\lambda_0 < L(x; s) < \lambda_1$ ,  $0 \leq s \leq t$ , we continue sampling.

Since each distribution of  $L(x; t)$  under  $H_i$ ,  $i=0, 1$ , is symmetric to the other, the thresholds  $-\lambda_0$  and  $\lambda_1$  must be, under the condition (2.4), symmetric, that is,  $\lambda_0 = \lambda_1$ .

Let  $F_t$  be the  $\sigma$ -field generated by  $\{W(s), 0 \leq s \leq t\}$  and let us put

$$y(t) = \int_0^t \phi(s) dw(s), \quad 0 \leq t < \infty. \quad (2.6)$$

Then we have

LEMMA 2.1.  $\{y(t), F_t, 0 \leq t < \infty\}$  is a Gaussian Martingale with the mean-value zero, its covariance function  $R_y(t, s) = V(\min(t, s))$  and its realizations are continuous with probability one.

PROOF. Clear.

From the symmetricity of the distribution of  $L(x; t)$ , we may and do proceed our discussion under the assumption that  $H_0$  is always true.

We have the following evaluation of the tail probability of  $\tau$ :

LEMMA 2.2. For sufficiently large  $t$ ,

$$P(\tau > t) \leq \frac{2}{\pi} \frac{\sqrt{V(t)}}{(V(t) - 2\lambda_0)} \exp\left\{-\frac{V(t) - 2\lambda_0}{8V(t)}\right\}. \quad (2.7)$$

PROOF. Since  $[\tau > t] \subset [|\gamma(t) - \frac{1}{2} V(t)| < \lambda_0]$ , we have from lemma 2.1,

$$P(\tau > t) \leq \int_{-\lambda_0 + \frac{1}{2} V(t)}^{\infty} \frac{1}{\sqrt{2\pi V(t)}} \exp\left[-\frac{y^2}{2V(t)}\right] dy.$$

For a large  $t$  such that  $V(t) > 2\lambda_0$ , the inequality (2.7) easily follows. Q. E. D.

LEMMA 2.3. *If there is a positive constant  $\alpha > 0$ , whatever small it is, such that the signal power  $V(t)$  diverges to infinity with the same order as  $O(t^\alpha)$  or faster, then for all positive  $\beta > 0$ ,  $E\{\tau^\beta\} < \infty$ .*

PROOF. Let  $F(t)$  be the c.d.f. of  $\tau$ . From the assumption that  $V(t) = O(t^\alpha)$ , we can find positive numbers  $T_0$  and  $A^*$  such that  $\sqrt{V(t)} - 2\lambda_0/\sqrt{V(t)} \geq A^*t^{\alpha/2}$ , for all  $t \geq T_0$ . It is enough for us to show that  $\int_{T_0}^{\infty} t^\beta dF(t) < \infty$ , for all  $\beta > 0$ . Indeed, it is easily seen that the integral is dominated by a convergent series  $K_0 \sum_{\nu=1}^{\infty} (1+\nu)^\beta e^{-K_1\nu^\alpha} < \infty$ , where  $K_0$  and  $K_1$  are suitably chosen positive constants. Q. E. D.

Let us put

$$U(t) = y(t)^2 - V(t), \quad 0 \leq t < \infty,$$

and for each  $\lambda$ ,  $-\infty < \lambda < \infty$ ,

$$Z(t, \lambda) = \exp \left\{ \lambda y(t) - \frac{\lambda^2}{2} V(t) \right\}, \quad 0 \leq t < \infty.$$

Then, we have

LEMMA 2.4.  $\{U(t), F_t, 0 \leq t < \infty\}$  is a martingale with the mean value zero and  $\{Z(t, \lambda), F_t, 0 \leq t < \infty\}$  is also a martingale with the mean value 1 for each real  $\lambda$ .

PROOF. It is clear that  $E\{U(t)\} = 0$ . Let us put  $\xi(s, t) = \int_s^t \phi(u) dW(u)$ . Then

$$U(t+h) = U(t) + 2y(t)\xi(t, t+h) + \{\xi(t, t+h)\}^2 - V(t+h) + V(t).$$

Thus, we have

$$E\{U(t+h) | F_t\} = U(t), \quad \text{a. s.}$$

On the other hand,  $E\{e^{\lambda y(t)}\} = \exp \left\{ -\frac{\lambda^2}{2} V(t) \right\}$ , and hence  $E\{Z(t, \lambda)\} \equiv 1$ , for each real  $\lambda$ . Since it is written as follows:

$$Z(t+h, \lambda) = Z(t, \lambda) \exp \left\{ \lambda \xi(t, t+h) - \frac{\lambda^2}{2} [V(t+h) - V(t)] \right\},$$

we have

$$E\{Z(t+h, \lambda) | F_t\} = Z(t, \lambda), \quad \text{a. s.}$$

This shows that  $\{Z(t, \lambda), F_t, 0 \leq t < \infty\}$  is a martingale for each real  $\lambda$ . Q. E. D.

By noticing that  $\tau$  is the Brownian stopping time, that is  $\{\tau > t\} \in F_t$  for each  $t$ , we have

- THEOREM 2.1. (i)  $E\{y(\tau)\} = 0$ ,  
(ii)  $E\{|y(\tau)|^2\} = E\{V(\tau)\}$ , and  
(iii)  $E\left\{\exp \left\{ \lambda y(\tau) - \frac{\lambda^2}{2} V(\tau) \right\}\right\} = 1$ , for each real  $\lambda$ .

PROOF. Let us define a sequence of stopping times  $\tau_n$  by

$$\tau_n = \min(n, \tau), \quad n = 1, 2, \dots$$

Let  $\check{y}_n(t)$ ,  $n = 1, 2, \dots$  be a sequence of stopped processes of  $y(t)$  by  $\tau_n$ , that is,  $\check{y}_n(t) = y(t)$  for  $t < \tau_n$ ;  $= y(\tau_n)$  for  $t \geq \tau_n$  and  $\check{\mathfrak{B}}_t^{(n)}$  the  $\sigma$ -field generated by  $\tau_n$ , that is,

the totality of measurable sets  $A$  whose intersection with  $\{\min(t, \tau_n) \leq s\}$  belongs to  $F_s$  for each  $s$ ,  $0 \leq s < \infty$ .

Since  $\tau_n$  is bounded a.s. for each  $n$ , it is seen that  $\{\check{y}_n(t), \check{\mathfrak{B}}_t^{(n)}, 0 \leq t < \infty\}$  is a martingale and  $E\{\check{y}_n(t)\} = \sup_{t'} E\{y(t')\} = 0$  for all  $t$ ,  $0 \leq t < \infty$ . (See [1]).

Hence, for all  $t > n$ , ( $n = 1, 2, \dots$ ),

$$\begin{aligned} E\{\check{y}_n(t)\} &= E\{y(\tau_n)\} = \int_{[\tau \leq n]} y(\tau) dP + \int_{[\tau > n]} y(n) dP \\ &= E\{y(t)\} = 0. \end{aligned}$$

Since for  $\tau > n$ ,  $|y(n)| \leq \lambda_0 + \frac{1}{2} V(n)$ , we have

$$\begin{aligned} \left| \int_{[\tau > n]} y(n) dP \right| &\leq \left( \lambda_0 + \frac{1}{2} V(n) \right) P(\tau > n) \\ &\leq \text{Const.} \times \frac{\sqrt{V(n)}(V(n) + 2\lambda_0)}{V(n) - 2\lambda_0} \exp \left\{ -\frac{(V(n) - 2\lambda_0)^2}{8V(n)} \right\} \\ &\longrightarrow 0 \quad \text{as } n \rightarrow \infty. \end{aligned}$$

Thus, we have

$$E\{y(\tau)\} = \lim_{n \rightarrow \infty} E\{y(\tau_n)\} = 0.$$

Similarly, we write

$$\begin{aligned} \check{U}_n(t) &= U(t) \quad \text{for } t < \tau_n \\ &= U(\tau_n) \quad \text{for } t \geq \tau_n \\ \check{Z}_n(t, \lambda) &= Z(t, \lambda) \quad \text{for } t < \tau_n \\ &= Z(\tau_n, \lambda) \quad \text{for } t \geq \tau_n. \end{aligned}$$

We have then new martingale processes  $\{\check{U}_n(t), \check{\mathfrak{B}}_t^{(n)}, 0 \leq t < \infty\}$  and  $\{\check{Z}_n(t, \lambda), \check{\mathfrak{B}}_t^{(n)}, 0 \leq t < \infty\}$ . Therefore we have

$$\begin{aligned} E\{U_n(t)\} &= \int_{[\tau \leq n]} U(\tau) dP + \int_{[\tau > n]} U(n) dP \\ &= \int_{[\tau \leq n]} \{y^2(\tau) - V(\tau)\} dP + \int_{[\tau > n]} \{y(n)^2 - V(n)\} dP \\ &= 0. \end{aligned}$$

Since,

$$\begin{aligned} \left| \int_{[\tau > n]} \{y(n)^2 - V(n)\} dP \right| &\leq \left\{ V(n) + \frac{1}{4} (2\lambda_0 + V(n))^2 \right\} \cdot P(\tau > n) \\ &\longrightarrow 0 \quad \text{as } n \rightarrow \infty, \end{aligned}$$

We have

$$\lim_{n \rightarrow \infty} \int_{[\tau \leq n]} [y^2(\tau) - V(\tau)] dP = E\{(y(\tau))^2\} - E\{V(\tau)\} = 0.$$

Similarly we have

$$1 = E\{\tilde{Z}_n(t, \lambda)\} = \int_{[\tau \leq n]} e^{\lambda y(\tau) - \frac{\lambda^2}{2} V(\tau)} dP \\ + \int_{[\tau > n]} e^{\lambda y(n) - \frac{\lambda^2}{2} V(n)} dP.$$

Since, for each real  $\lambda$ ,

$$\left| \int_{[\tau > n]} \exp \left\{ \lambda y(n) - \frac{\lambda^2}{2} V(n) \right\} dP \right| \\ \leq \text{Const.} \times \frac{\sqrt{V(n)}}{|V(n) - 2\lambda_0|} \times \exp \left\{ -\frac{1}{8} \left[ (1 - 2\lambda)^2 V(n) - 4\lambda_0 + \frac{4\lambda_0^2}{V(n)} \right] \right\} \\ \longrightarrow 0 \quad \text{as } n \rightarrow \infty,$$

it follows immediately that for each real  $\lambda$

$$1 = \lim_{n \rightarrow \infty} \int_{[\tau \leq n]} \exp \left\{ \lambda y(\tau) - \frac{\lambda^2}{2} V(\tau) \right\} dP \\ = E \left\{ \exp \left\{ \lambda y(\tau) - \frac{\lambda^2}{2} V(\tau) \right\} \right\}. \quad \text{Q. E. D.}$$

EXAMPLE 2.1. (c.f. [2], [7]). From theorem 2.1, it is easily obtain the A.S. N.'s  $E\{\tau|H_0\}$  and  $E\{\tau|H_1\}$  of our detection problem when the signal  $\phi(s)$  is constant  $\alpha > 0$  which is in the white noise. From (2, 4), it is well known that  $\lambda_0$  is given by

$$\lambda_0 = \log \left( \frac{1-\gamma}{\gamma} \right).$$

Let  $E_1 = \{W(\tau) = \frac{\lambda_0}{\alpha} + \frac{\alpha}{2}\}$  and  $E_2$  be the complementary event of  $E_1$ . Ther., since  $\tau$  is define by

$$\tau = \inf \left\{ t > 0; \left| W(t) - \frac{\alpha}{2} t \right| \geq \lambda_0 / \alpha \right\},$$

we have

$$E\{y(\tau)\} = \gamma E \left\{ \lambda_0 + \frac{\alpha^2}{2} \cdot \tau | E_1 \right\} + (1-\gamma) E \left\{ -\lambda_0 + \frac{\alpha^2}{2} \cdot \tau | E_2 \right\} \\ = \frac{\alpha^2}{2} E\{\tau\} - (1-2\gamma)\lambda_0 = 0,$$

that is,

$$E\{\tau\} = E\{\tau|H_0\} = E\{\tau|H_1\} \\ = \frac{2}{\alpha^2} (1-2\gamma) \log \left( \frac{1-\gamma}{\gamma} \right). \quad (2.8)$$

EXAMPLE 2.2. Let  $\Delta > 0$  be a suitably chosen small interval and let us put

$$\phi_j(s) = 1 \quad \text{for } (j-1)\Delta \leq s < j\Delta, \quad j = 1, 2, \dots, \\ = 0 \quad \text{otherwise.}$$

Let us assume that  $\phi(s)$  is a pulsed signal and is approximately expressed by

$$\phi(s) = \sum_{j=1}^{\infty} h \cdot \epsilon_j \cdot \phi_j(s), \quad 0 \leq s < \infty,$$

where  $h > 0$  is a given constant and  $\varepsilon_j = 0$  or  $1$ ,  $j = 1, 2, 3, \dots$ .

We also assume that a relative frequency of the occurrence of pulses  $(\varepsilon_1 + \varepsilon_2 + \dots + \varepsilon_n)/n$  is close to a constant  $a$ , ( $0 < a \leq 1$ ), except for the first several  $n$ .

Then, we have approximately

$$V(t) \doteq \alpha^2 a t, \quad \text{and} \quad y(t) = h \sum_{j=1}^n \varepsilon_j z_j + h \varepsilon_{n+1} [W(t) - W(n\Delta)], \quad (2.9)$$

where  $z_j = W(j\Delta) - W((j-1)\Delta)$  and  $n$  is the largest integer not greater than  $t/\Delta$ .

It is clear that  $\{y(t), 0 \leq t < \infty\}$  is a Gaussian process with the mean value zero and its covariance function  $R(s, t)$  is given approximately by

$$R(s, t) \doteq ah^2 \min(s, t).$$

Hence, this detection problem of the pulsed signal  $\phi(s)$  in the white noise is nearly equivalent to the problem to detect a constant signal  $\phi_0(s) \equiv h \cdot \sqrt{a}$  in the white noise as shown in Example 2.1.

Thus, we have the A.S.N. which are given approximately by

$$E\{\tau | H_0\} = E\{\tau | H_1\} \doteq \frac{2(1-2\gamma)}{ah^2} \cdot \log\left(\frac{1-\gamma}{\gamma}\right).$$

### § 3. Detection of a constant signal in a non-white Gaussian noise.

Similary in § 2, let  $\{W(s), F_s, 0 \leq s < \infty\}$  be the Wiener process.

Let  $\{\xi(s), 0 \leq s < \infty\}$  be a Gaussian noise process defined by

$$\xi(t) = \int_0^t e^{-\beta(t-u)} dW(u), \quad 0 \leq t < \infty, \dots \quad (3.1)$$

where  $\beta \geq 0$  is a non-negative constant.

We shall consider the following detection problem;

$$\begin{aligned} H_0: \quad x(t) &= \xi(t), \\ H_1: \quad x(t) &= \alpha t + \xi(t), \end{aligned} \quad (3.2)$$

where  $\alpha > 0$ , is a constant signal to be detected.

Let  $P_{it}$ ,  $i = 0, 1$ , be the distribution of the observation  $\{x(s), 0 \leq s \leq t\}$  under  $H_i$ ,  $i = 0, 1$ , respectively.

Then, the detection problem (3.2) is nonsingular and the logarithm of the likelihood ratio of  $P_{1t}$  with respect to  $P_{0t}$  is given by

$$\begin{aligned} L(x; t) &= \log \frac{dP_{1t}}{dP_{0t}}(x) \\ &= L_0(x; t) + \frac{\beta}{2} \cdot \{2m(t)x(t) - (m(t))^2\} \\ &\quad + \frac{\beta^2}{2} \cdot \left\{ 2 \int_0^t m(s)x(s)ds - \int_0^t (m(s))^2 ds \right\}, \end{aligned} \quad (3.3)$$

where  $m(t) = \alpha t$ , and

$$L_0(x; t) = \alpha x(t) - \frac{\alpha^2}{2} t. \quad (3.4)$$

Suppose that we adopt  $L_0(x; t)$  as a statistic for the problem (3.2) instead of the log-likelihood ratio  $L(x; t)$ .

$L_0(x; t)$  is actually not optimal for the problem (3.2) (See [3]) but it has several sub-optimal properties because it become optimal when  $\beta = 0$ , that is, the noise  $\xi(t)$  were white, and  $L_0(x; t)$  does not contain the parameter  $\beta$  which is intrinsic in the noise.

We set error probabilities to the equal to the prescribed value  $\gamma$ , that is,

$$P(\text{to accept } H_1 | H_0) = P(\text{to accept } H_0 | H_1) = \gamma, \quad (3.5)$$

and consider only such decision rules that (3.5) holds.

We define a stopping  $\tau^*$  by

$$\tau^* = \inf \{t > 0; L_0(x; t) \leq -\lambda_0 \text{ or } L_0(x; t) \geq \lambda_1\} \quad (3.6)$$

where  $\lambda_0, \lambda_1$  are positive constants such that our following decision rule satisfies (3.5).

Our decision rule based on the observation  $\{x(s), 0 \leq s \leq t\}$  will be formulated as follows; When  $L_0(x; \tau^*) = \lambda_1$ , (or  $-\lambda_0$ ), we stop sampling at  $t = \tau^*$  and decide  $H_1$ , (or  $H_0$ ) to be true, while as long as  $-\lambda_0 < L_0(x, s) < \lambda_1$ ,  $0 \leq s \leq t$ , we continue sampling.

Since each distribution of  $L_0(x; t)$  under  $H_i$ ,  $i = 0, 1$ , is symmetric to the other, the constants  $\lambda_0$  and  $\lambda_1$  must be equal under the condition (3.5).

Let us put

$$V(t) = E\{\xi(t)^2\} = (1 - e^{-2\beta t})/2\beta.$$

Let us consider a continuous function  $f(t)$ ,  $0 \leq t < \infty$ , such that

- (i)  $f(0) = -\lambda^* < 0$ ,
- (ii)  $f(t) = O(t^\alpha) \nearrow \infty$  as  $t \rightarrow \infty$ ,

for some positive constant  $\alpha > 0$ .

We shall now define a stopping time  $\tau$  as follows;

$$\tau = \inf \{t > 0; \xi(t) \leq f(t) \text{ or } \xi(t) \geq 2\lambda^* + f(t)\}. \quad (3.7)$$

The stopping time  $\tau^*$  defined by (3.6) is a special case of  $\tau$  by (3.7). Indeed,  $\tau^*$  corresponds to the case where  $f(t) = \alpha t/2 - \lambda^*$  and  $\lambda^* = \lambda_0/\alpha$ .

For a large  $t$ , it is easily seen that

$$\begin{aligned} P(\tau \geq t) &\leq P(f(t) \leq \xi(t) \leq 2\lambda^* + f(t)) \\ &\leq P(\xi(t) \geq f(t)) \\ &\leq \frac{1}{2\sqrt{\pi\beta}} \times \frac{1}{|f(t)|} \times \exp\{-\beta \times [f(t)]^2\}. \end{aligned}$$

Thus, we have



LEMMA 3.1. For all real  $k \geq 0$ ,

$$E\{\tau^k\} < \infty.$$

Proof of lemma 3.1 is analogous to that of lemma 2.3.

Now, we obtain

THEOREM 3.1. Let  $\tau$  be defined by (3.7). Then we have

$$(i) \quad E\{\xi(\tau)\} = 0,$$

$$(ii) \quad E\{\xi(\tau)^2\} = E\{V(\tau)\}, \quad \text{and}$$

$$(iii) \quad \text{for each real } \lambda,$$

$$E\left\{\exp\left[\lambda\xi(\tau) - \frac{\lambda^2}{2} V(\tau)\right]\right\} = 1. \quad (3.8)$$

PROOF. It is clear that  $\tau$  is a stopping time with respect to  $F_t$ ,  $t \geq 0$ . The stochastic process  $\{\xi(t), 0 \leq t < \infty\}$  is the unique non-anticipated solution of a stochastic differential equation;

$$d\xi(t) = -\beta\xi(t)dt + dW(t), \quad (3.9)$$

with  $\xi(0) = 0$ . Hence, it enjoys the strong Markov property with respect to a Brownian stopping time, for example, say,  $\tau$ . (See [4]).

For any random variable  $g$  and any measurable set  $A$ , we will write

$$E_A\{g\} = E\{I_A \cdot g\},$$

where  $I_A$  is the indicator function of  $A$ .

Let  $\mathfrak{B}_\tau$  be the  $\sigma$ -field generated by  $\tau$ , that is, the totality of sets whose intersections with  $[\tau > t]$  belong to  $F_t$  for every  $t$ ,  $0 \leq t < \infty$ . Then, we have from the strong Markov property,

$$\begin{aligned} E_{[\tau \leq t]} \{\xi(t)\} &= E\{E\{I_{[\tau \leq t]} \cdot \xi(t) | \mathfrak{B}_\tau\}\} \\ &= E\{I_{[\tau \leq t]} \cdot E\{\xi(t) | \tau, \xi(\tau)\}\} \\ &= E_{[\tau \leq t]} \{\xi(\tau)\}. \end{aligned}$$

Since for  $\tau > t$ ,  $f(t) < \xi(t) < 2\lambda^* + f(t)$ , we have

$$\begin{aligned} |E_{[\tau > t]} \{\xi(t)\}| &\leq [2\lambda^* + f(t)] \cdot P(\tau > t) \\ &\leq \frac{1}{2\sqrt{\pi\beta}} \times \frac{|2\lambda^* + f(t)|}{|f(t)|} \times \exp\{-\beta|f(t)|^2\} \\ &\longrightarrow 0 \quad \text{as } t \rightarrow \infty. \end{aligned}$$

Thus, it is seen that

$$\begin{aligned} E\{\xi(t)\} &= \lim_{t \rightarrow \infty} E_{[\tau \leq t]} \{\xi(\tau)\} + \lim_{t \rightarrow \infty} E_{[\tau > t]} \{\xi(t)\} \\ &= E\{\xi(\tau)\} = 0. \end{aligned}$$

We have shown that (i) holds.

Let us write

$$U(t) = \xi(t)^2 - V(t).$$

Then,  $U(t)$  is a functional of the Markov process  $\{\xi(s), 0 \leq s < \infty\}$  and hence we have

$$\begin{aligned} E_{[\tau \leq t]} \{U(t)\} &= E\{E\{I_{[\tau \leq t]} \cdot U(t) | \mathfrak{B}_\tau\}\} \\ &= E\{I_{[\tau \leq t]} \cdot E\{U(t) | \tau, \xi(\tau)\}\} \\ &= E_{[\tau \leq t]} \{U(\tau)\} = E_{[\tau \leq t]} \{\xi(\tau)^2 - V(\tau)\}. \end{aligned}$$

Since, for  $\tau > t$ ,  $|\xi(t)| \leq 2\lambda^* + f(t)$ , it follows that

$$\begin{aligned} |E_{[\tau > t]} \{U(t)\}| &\leq [V(t) + (2\lambda^* + f(t))^2] \cdot P(\tau > t) \\ &\leq \frac{1}{2\sqrt{\pi}\beta} \cdot \frac{[V(t) + (2\lambda^* + f(t))^2]}{|f(t)|} \cdot e^{-\beta|f(t)|^2} \\ &\longrightarrow 0 \quad \text{as } t \rightarrow \infty. \end{aligned}$$

Thus, we have

$$\begin{aligned} E\{U(t)\} &= \lim_{t \rightarrow \infty} E_{[\tau \leq t]} \{U(\tau)\} + \lim_{t \rightarrow \infty} E_{[\tau > t]} \{U(t)\} \\ &= E\{\xi(\tau)^2 - V(\tau)\} = 0. \end{aligned}$$

We have shown that  $E\{\xi(\tau)^2\} = E\{V(\tau)\}$ .

Let us put for each real  $\lambda$ ,

$$Z(t, \lambda) = \exp\left[\lambda\xi(t) - \frac{\lambda^2}{2} V(t)\right], \quad 0 \leq t < \infty.$$

Then, it is clear that  $Z(t, \lambda)$  is  $F_t$ -measurable and  $E\{Z(t, \lambda)\} \equiv 1$ .

Thus, we have

$$\begin{aligned} E_{[\tau \leq t]} \{Z(t, \lambda)\} &= E\{E\{I_{[\tau \leq t]} Z(t, \lambda) | \mathfrak{B}_\tau\}\} \\ &= E\{I_{[\tau \leq t]} E\{Z(t, \lambda) | \tau, \xi(\tau)\}\} \\ &= E_{[\tau \leq t]} \{Z(\tau, \lambda)\}. \end{aligned}$$

Now, we shall evaluate  $E_{[\tau > t]} \left\{ \exp\left[\lambda\xi(t) - \frac{\lambda^2}{2} V(t)\right] \right\}$ .

Since, for  $\tau > t$ ,  $f(t) < \xi(t) < 2\lambda^* + f(t)$ , we have for each non-negative real  $\lambda$ ,

$$\begin{aligned} E_{[\tau > t]} \{Z(t, \lambda)\} &\leq \exp\left\{\lambda[2\lambda^* + f(t)] - \frac{\lambda^2}{2} V(t)\right\} \cdot P(\tau > t) \\ &\leq \frac{1}{2|f(t)|\sqrt{\pi}\beta} \exp\left\{2\lambda\lambda^* - \beta|f(t)|^2\left(1 - \frac{\lambda}{\beta f(t)}\right)\right\} \\ &\longrightarrow 0 \quad \text{as } t \rightarrow \infty, \end{aligned}$$

and for each negative real  $\lambda$ ,

$$\begin{aligned} E_{[\tau > t]} \{Z(t, \lambda)\} &\leq \exp\left\{\lambda f(t) - \frac{\lambda^2}{2} V(t)\right\} \\ &\longrightarrow 0 \quad \text{as } t \rightarrow \infty. \end{aligned}$$

Thus, it follows that for each real  $\lambda$ ,

$$\begin{aligned} E\{Z(t, \lambda)\} &= \lim_{t \rightarrow \infty} E_{[\tau \leq t]} \{Z(\tau, \lambda)\} + \lim_{t \rightarrow \infty} E_{[\tau > t]} \{Z(t, \lambda)\} \\ &= E\{Z(\tau, \lambda)\} \equiv 1. \end{aligned}$$

This completes the proof of theorem 3.1.

Q. E. D.

The stopping time  $\tau^*$  is the special case of  $\tau$  in (3.7) and hence from theorem 3.1 it is seen that

$$\begin{aligned} E\{\xi(\tau^*)\} &= 0, \\ E\{\xi(\tau^*)^2\} &= E\{V(\tau^*)\}, \end{aligned}$$

and for each real  $\lambda$ ,

$$E\left\{\exp\left[\lambda\xi(\tau^*) - \frac{\lambda^2}{2} V(\tau^*)\right]\right\} \equiv 1.$$

COROLLARY.

$$E\{\tau^*|H_0\} = E\{\tau^*|H_1\} = 2\lambda_0(1-2\gamma)/\alpha^2,$$

where  $\lambda_0$  is such a constant that the error probabilities satisfy (3.5).

PROOF. Let  $E_0 = \{\xi(\tau^*) = \frac{\alpha}{2}\tau^* - \frac{\lambda_0}{\alpha}\}$  and  $E_1$  be the complementary event of  $E_0$ .

Then, by noticing that  $\tau^*$  is equal to  $\tau$  when  $f(t) = \frac{\alpha}{2}t - \lambda^*$  and  $\lambda^* = \lambda_0/\alpha$ . and also that  $P(E_1|H_0) = \gamma$  and  $P(E_0|H_0) = 1 - \gamma$ , it follows from theorem 3.1 that

$$\begin{aligned} E\{\xi(\tau^*)\} &= \frac{\alpha}{2} [E\{\tau^*|E_0\} \cdot P(E_0|H_0) + E\{\tau^*|E_1\} \cdot P(E_1|H_0)] \\ &\quad - \frac{\lambda_0}{\alpha} P(E_0|H_0) + \frac{\lambda_0}{\alpha} P(E_1|H_0) \\ &= \frac{\alpha}{2} E\{\tau^*|H_0\} - \frac{\lambda_0}{\alpha} (1-2\gamma) = 0. \end{aligned}$$

Thus, we have proved corollary.

Q. E. D.

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